Atlas Scientific™
Environmental Robotics

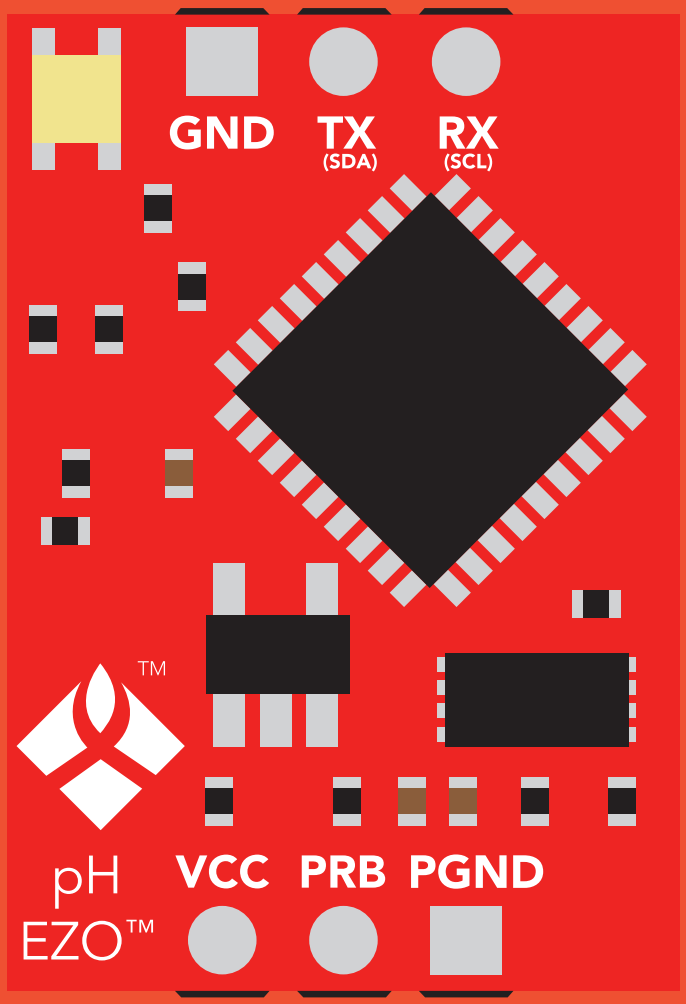
V 5.7

Revised 6/20

EZO-pH™

Embedded pH Circuit

Reads	**pH**
Range	**.001 – 14.000**
Resolution	**.001**
Accuracy	**+/– 0.002**
Response time	**1 reading per sec**
Supported probes	**Any type & brand**
Calibration	**1, 2, 3 point**
Temp compensation	**Yes**
Data protocol	**UART & I²C**
Default I²C address	**99 (0x63)**
Operating voltage	**3.3V – 5V**
Data format	**ASCII**



RoHS COMPLIANT

PATENT PROTECTED

Written by Jordan Press
Designed by Noah Press

This is an evolving document, check back for updates.

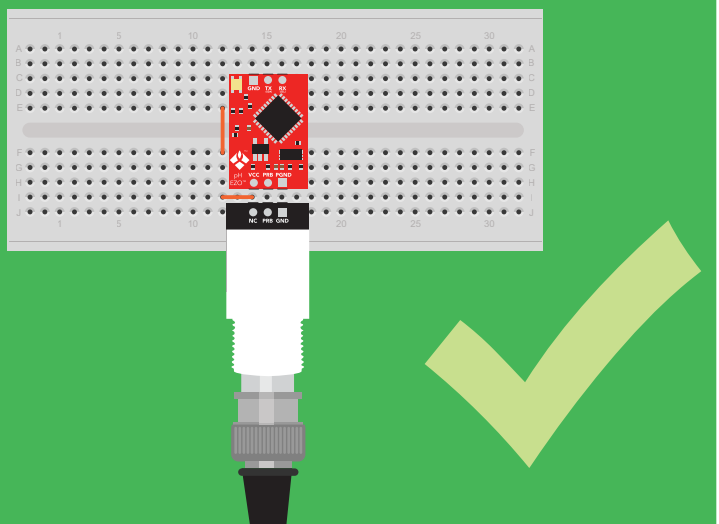
STOP

SOLDERING THIS DEVICE VOIDS YOUR WARRANTY.

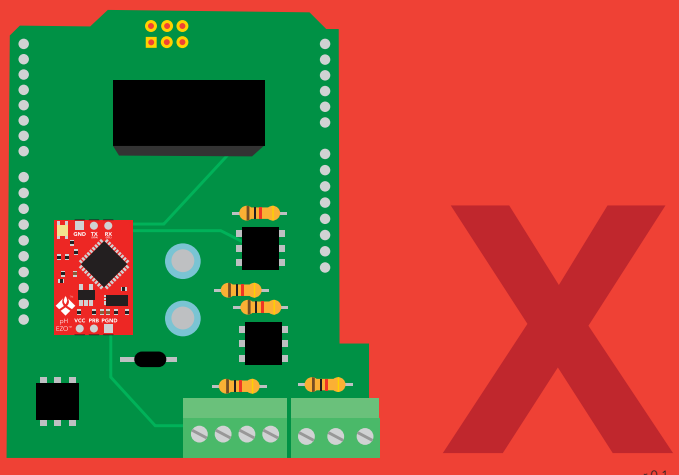
This is sensitive electronic equipment. Get this device working in a solderless breadboard first. Once this device has been soldered it is no longer covered by our warranty.

This device has been designed to be soldered and can be soldered at any time. Once that decision has been made, Atlas Scientific no longer assumes responsibility for the device's continued operation. The embedded systems engineer is now the responsible party.

Get this device working in a solderless breadboard first!



Do not embed this device without testing it in a solderless breadboard!



r 0.1

Table of contents

Circuit dimensions 4
Power consumption 4
Absolute max ratings 4
Operating principle 5
Power and data isolation 6
Correct wiring 8
Calibration theory 11
Default state 14
Available data protocols 15

UART

UART mode 17
Receiving data from device 18
Sending commands to device 19
LED color definition 20
UART quick command page 21
LED control 22
Find 23
Continuous reading mode 24
Single reading mode 25
Calibration 26
Export calibration 27
Import calibration 28
Slope 29
Extended pH scale 30
Temperature compensation 31
Naming device 32
Device information 33
Response codes 34
Reading device status 35
Sleep mode/low power 36
Change baud rate 37
Protocol lock 38
Factory reset 39
Change to I²C mode 40
Manual switching to I²C 41

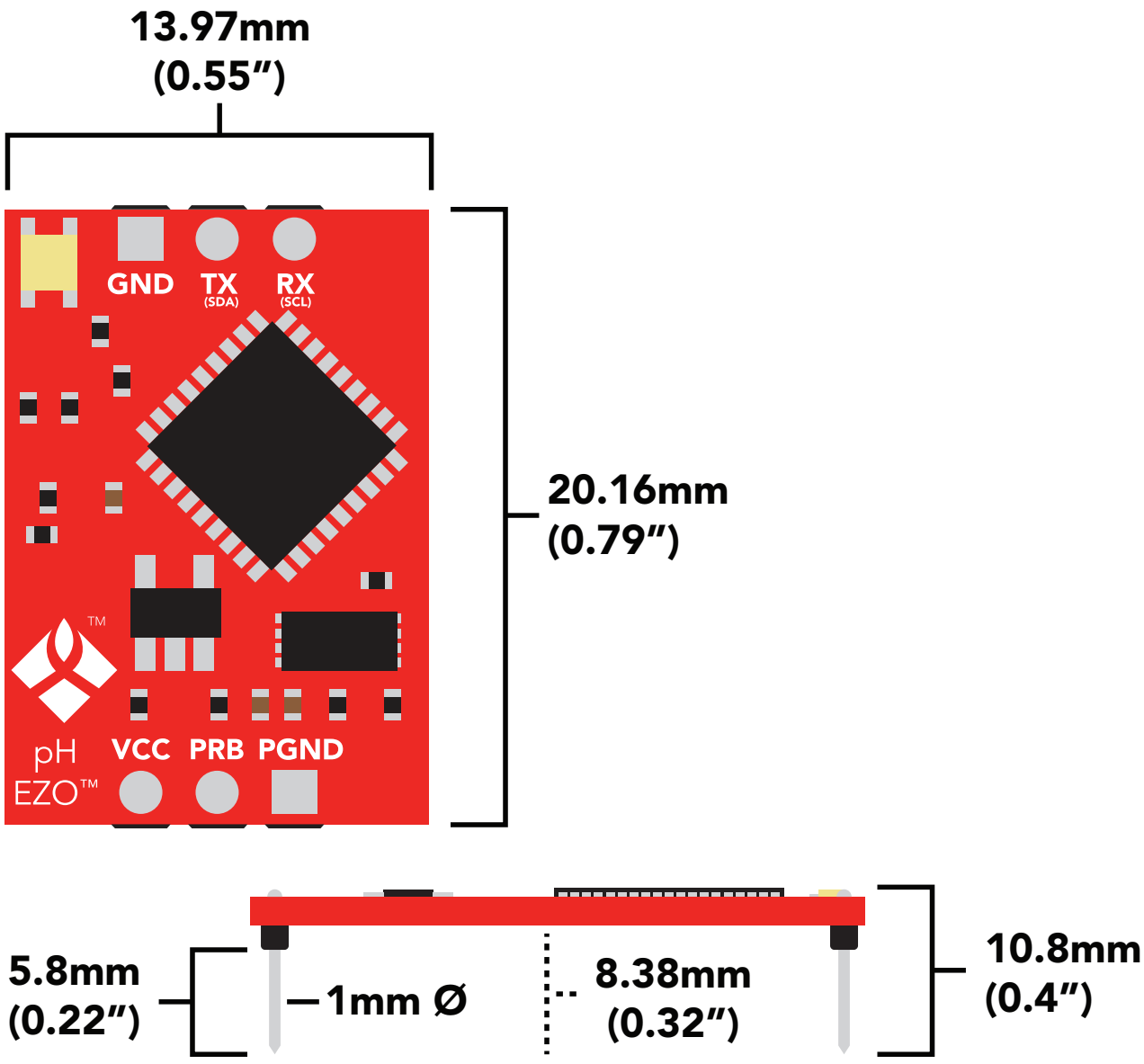
I²C

I²C mode 43
Sending commands 44
Requesting data 45
Response codes 46
LED color definition 47
I²C quick command page 48
LED control 49
Find 50
Taking reading 51
Calibration 52
Export calibration 53
Import calibration 54
Slope 55
Extended pH scale 56
Temperature compensation 57
Naming device 58
Device information 59
Reading device status 60
Sleep mode/low power 61
Protocol lock 62
I²C address change 63
Factory reset 64
Change to UART mode 65
Manual switching to UART 66

Circuit footprint 67
Datasheet change log 68
Warranty 71

Atlas Scientific™ Environmental Robotics

EZO™ circuit dimensions



Power consumption

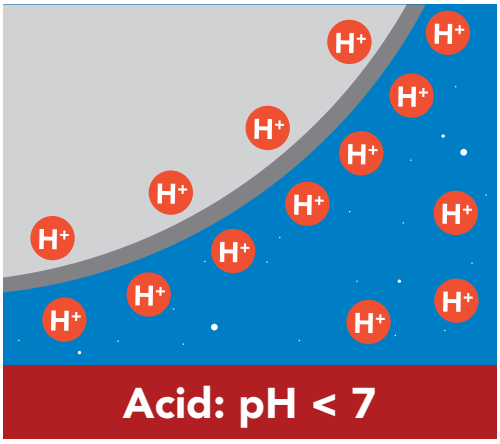
	LED	MAX	STANDBY	SLEEP
5V	ON	18.3 mA	16 mA	1.16 mA
	OFF	13.8 mA	13.8 mA	
3.3V	ON	14.5 mA	13.9 mA	0.995 mA
	OFF	13.3 mA	13.3 mA	

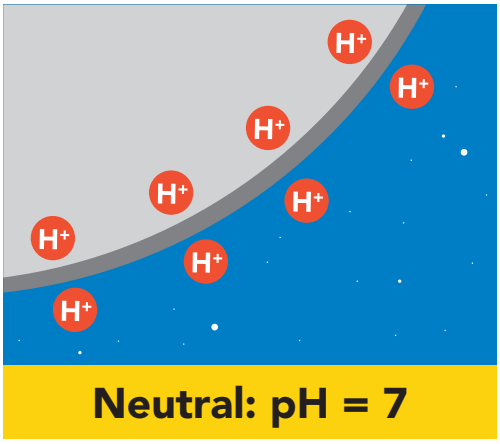
Absolute max ratings

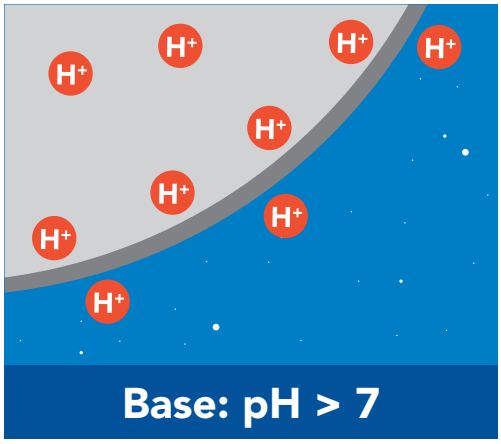
Parameter	MIN	TYP	MAX
Storage temperature (EZO™ pH)	-65 °C		125 °C
Operational temperature (EZO™ pH)	-40 °C	25 °C	85 °C
VCC	3.3V	5V	5.5V

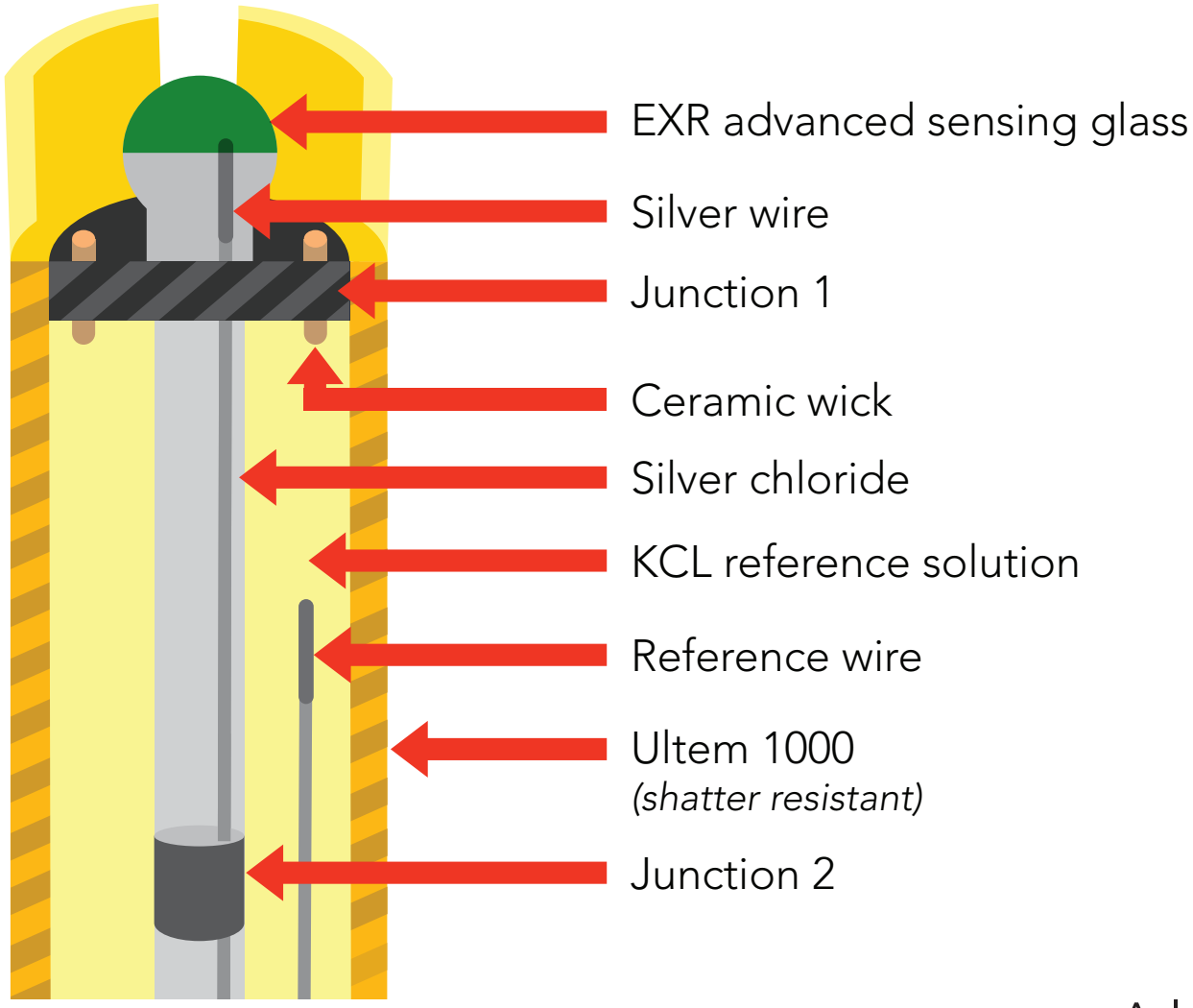
Operating principle

A pH ***(potential of Hydrogen)*** probe measures the hydrogen ion activity in a liquid. At the tip of a pH probe is a glass membrane. This glass membrane permits hydrogen ions from the liquid being measured to defuse into the outer layer of the glass, while larger ions remain in the solution. The difference in the concentration of hydrogen ions (outside the probe vs. inside the probe) creates a VERY small current. This current is proportional to the concentration of hydrogen ions in the liquid being measured.







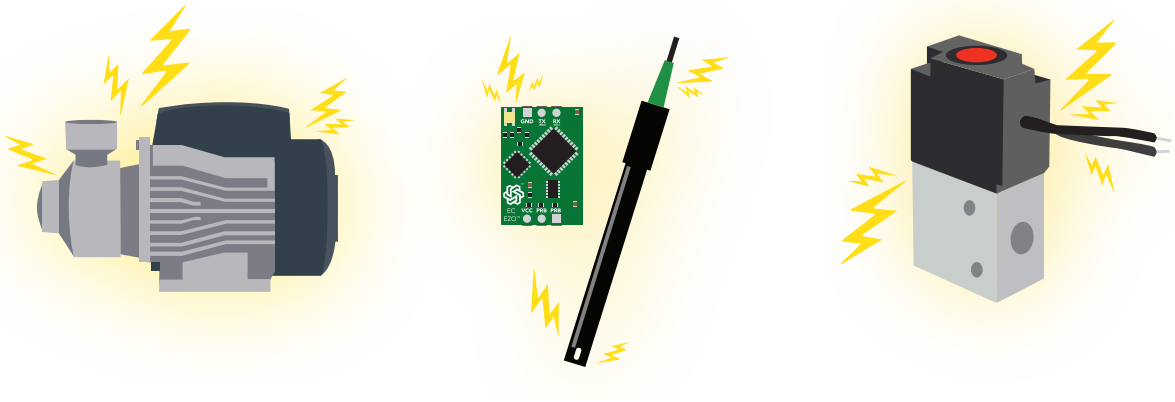


AtlasScientific™
Environmental Robotics

Power and data isolation

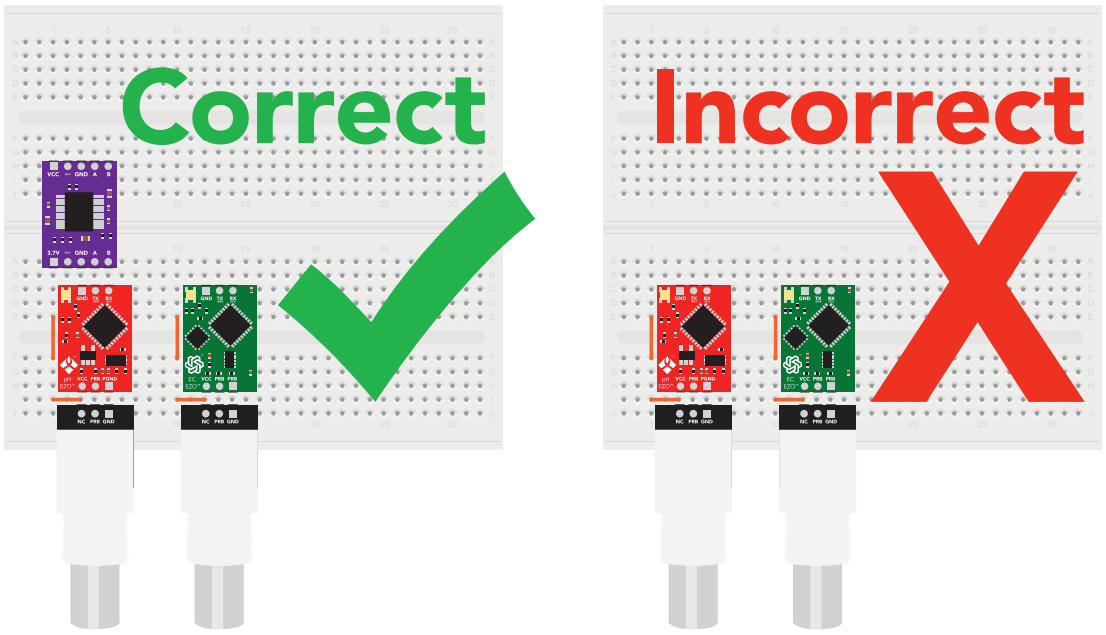
The Atlas Scientific EZO™ pH circuit is a very sensitive device. This sensitivity is what gives the pH circuit its accuracy. This also means that the pH circuit is capable of reading micro-voltages that are bleeding into the water from unnatural sources such as pumps, solenoid valves or other probes/sensors.

When electrical noise is interfering with the pH readings it is common to see rapidly fluctuating readings or readings that are consistently off. To verify that electrical noise is causing inaccurate readings, place the pH probe in a cup of water by itself. The readings should stabilize quickly, confirming that electrical noise was the issue.



When reading pH and Conductivity or Dissolved Oxygen together, it is ***strongly recommended*** that the EZO™ pH circuit is electrically isolated from the EZO™ Conductivity or Dissolved Oxygen circuit.

Basic EZO™ Inline Voltage Isolator



Without isolation, Conductivity and Dissolved Oxygen readings will effect pH accuracy.

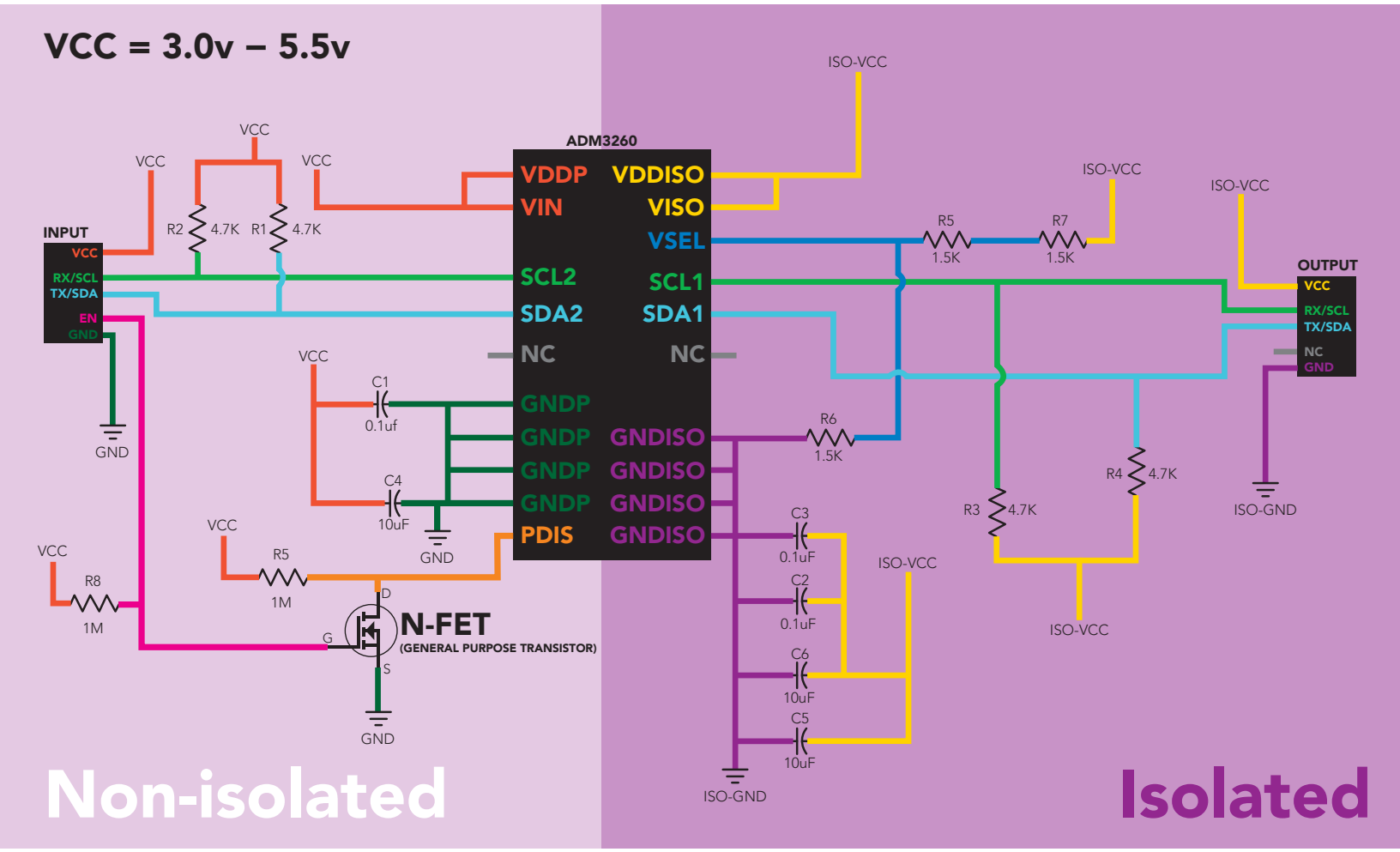
AtlasScientific™ Environmental Robotics

r 0.1

This schematic shows exactly how we isolate data and power using the ADM3260 and a few passive components. The ADM3260 can output isolated power up to 150 mW and incorporates two bidirectional data channels.

This technology works by using tiny transformers to induce the voltage across an air gap. PCB layout requires special attention for EMI/EMC and RF Control, having proper ground planes and keeping the capacitors as close to the chip as possible are crucial for proper performance. The two data channels have a 4.7kΩ pull up resistor on both the isolated and non-isolated lines (R1, R2, R3, and R4) The output voltage is set using a voltage divider (R5, R6, and R,7) this produces a voltage of 3.9V regardless of your input voltage.

Isolated ground is different from non-isolated ground, these two lines should not be connected together.

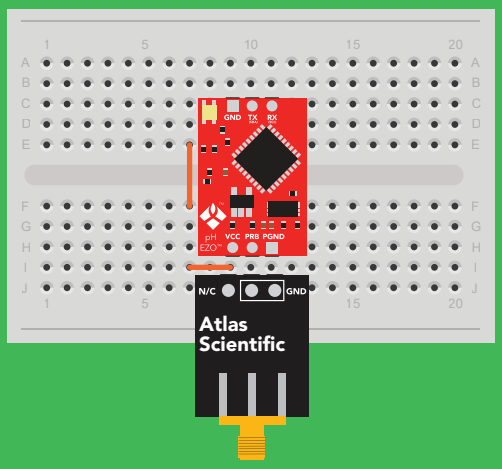


Correct wiring

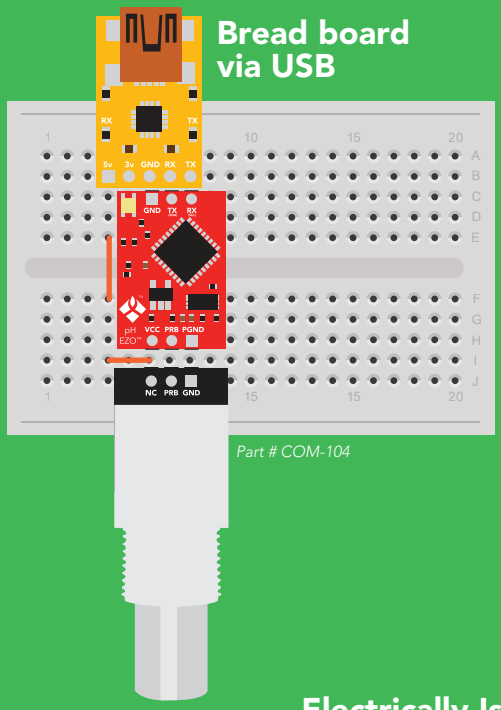
Carrier board

USB carrier board

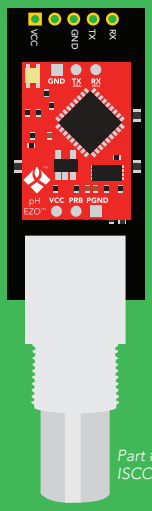
Bread board



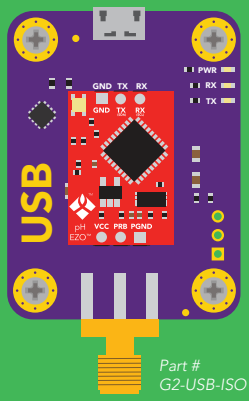
Bread board via USB



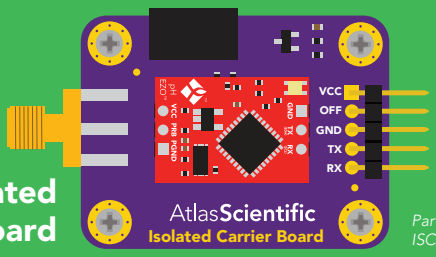
Part # COM-104



Part # ISCCB



Part # G2-USB-ISO

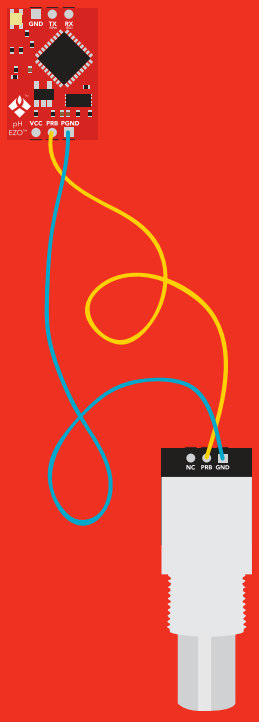


Electrically Isolated EZO™ Carrier Board

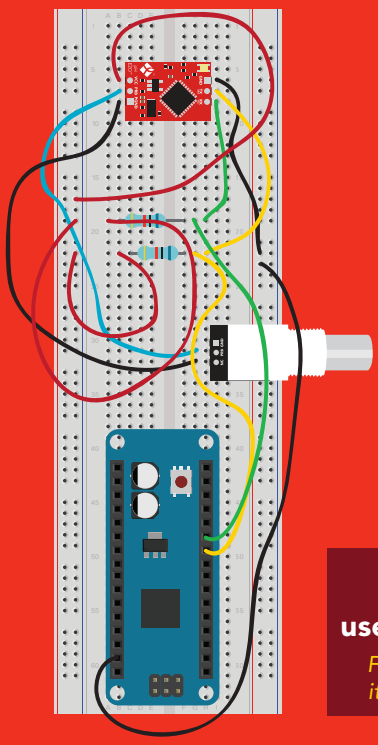
Part # ISCCB-2

Incorrect wiring

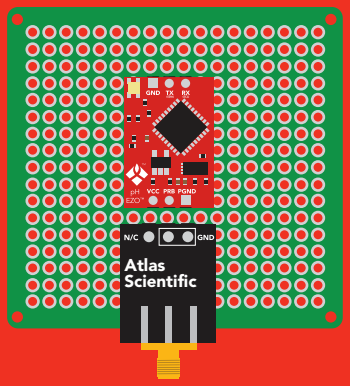
Extended leads



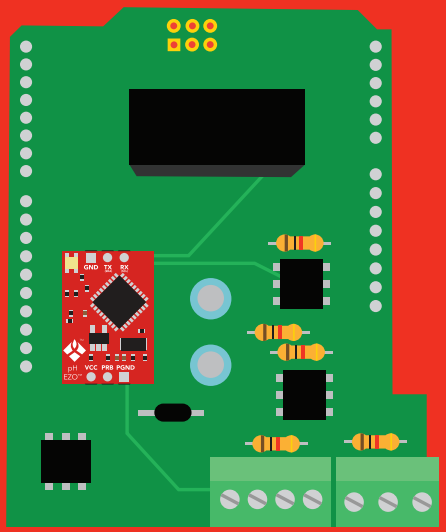
Sloppy setup



Perfboards or Protoboards



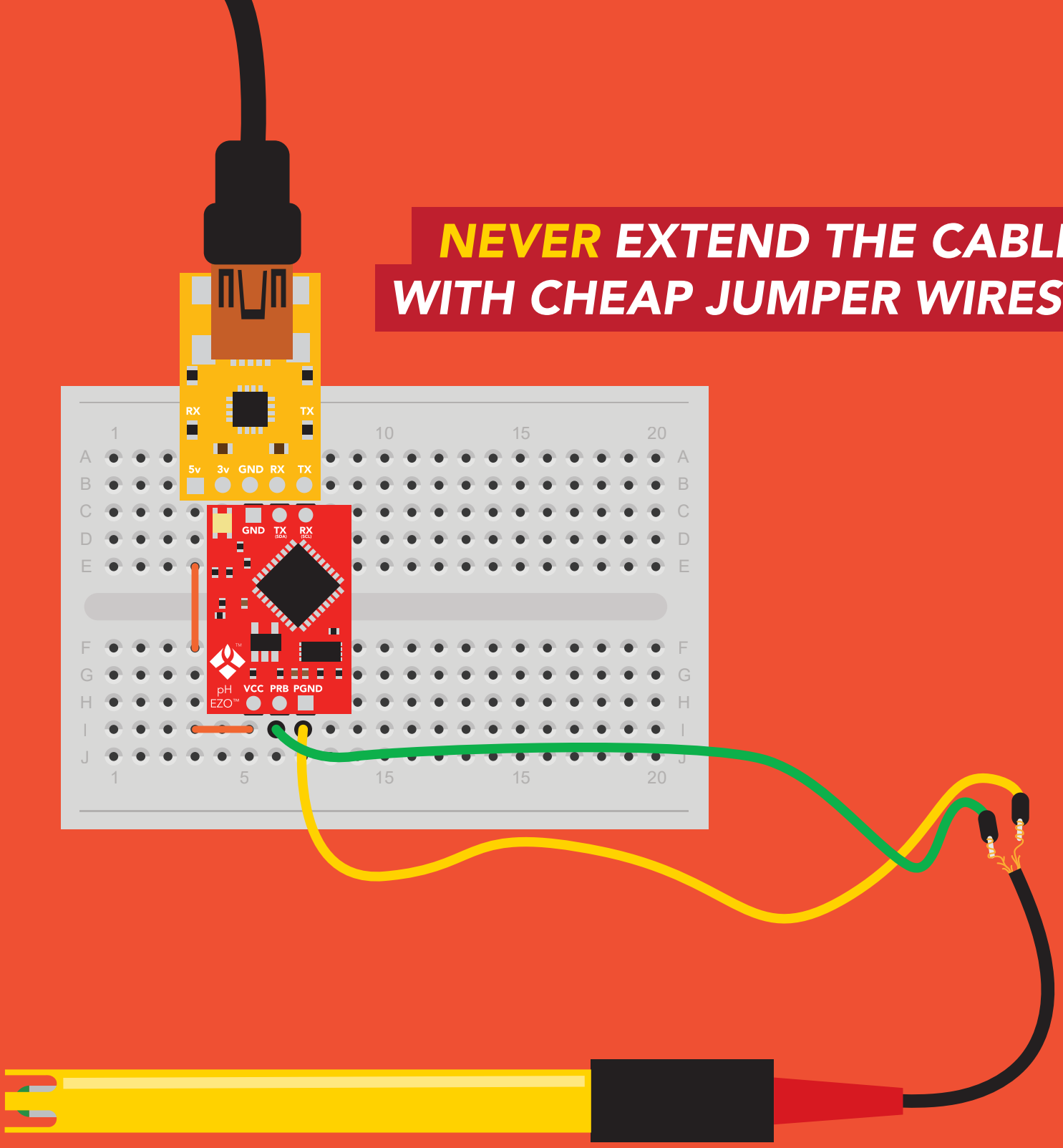
*Embedded into your device



NEVER
use Perfboards or Protoboards
Flux residue and shorting wires make it very hard to get accurate readings.

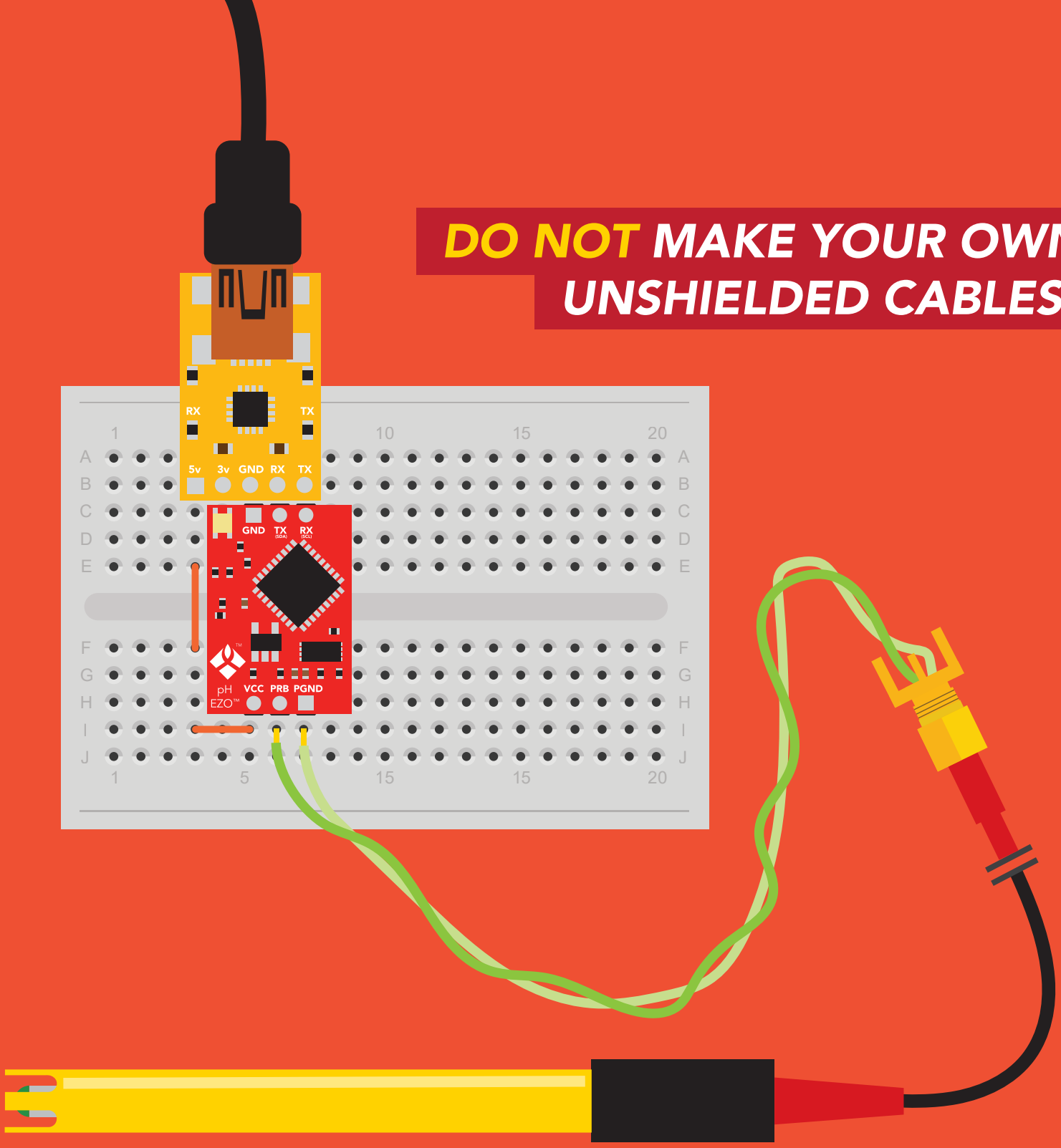
***Only after you are familar with EZO™ circuits operation**

AtlasScientific™
Environmental Robotics
r 0.1



NEVER EXTEND THE CABLE WITH CHEAP JUMPER WIRES!

DO NOT CUT THE PROBE CABLE WITHOUT REFERING TO THIS DOCUMENT!



ONLY USE SHIELDED CABLES.

Atlas Scientific™
Environmental Robotics

Calibration theory

Simple calibration

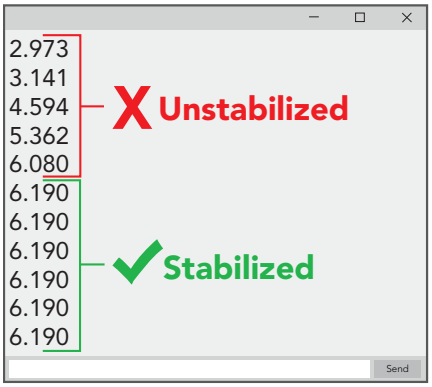
UART mode

Continuous readings

Advanced calibration

I²C mode

Continuously request readings



The most important part of calibration is watching the readings during the calibration process.

It's easiest to calibrate the device in its default state (UART mode, with continuous readings enabled).

Switching the device to I²C mode after calibration ***will not*** affect the stored calibration. If the device must be calibrated in I²C mode be sure to ***continuously request readings*** so you can see the output from the probe.

Calibration order

If this is your first time calibrating the EZO™ pH circuit, we recommend that you follow this calibration order.

1 **Mid point**

2 **Low point**

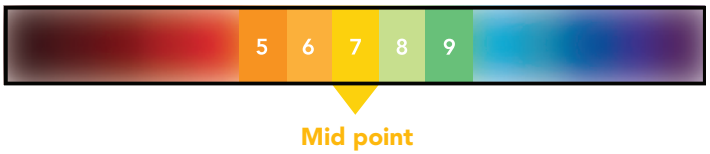
3 **High point**

AtlasScientific™ Environmental Robotics

Single, Two point, or Three point calibration

No calibration

Single point calibration



Two point calibration

Three point calibration

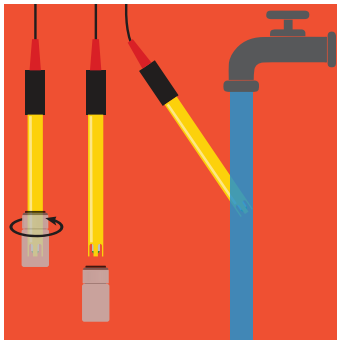
Two point calibration will provide high accuracy between **7.00** and the second point calibrated against, such as a **4.00**.

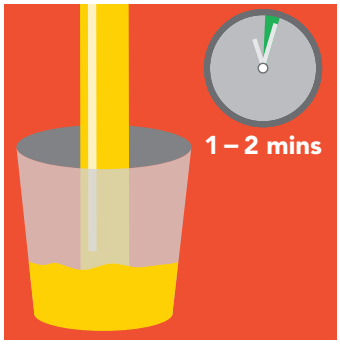
Three point calibration will provide high accuracy over the full pH range. Three point calibration at **4.00**, **7.00** and **10.00** should be considered the standard.

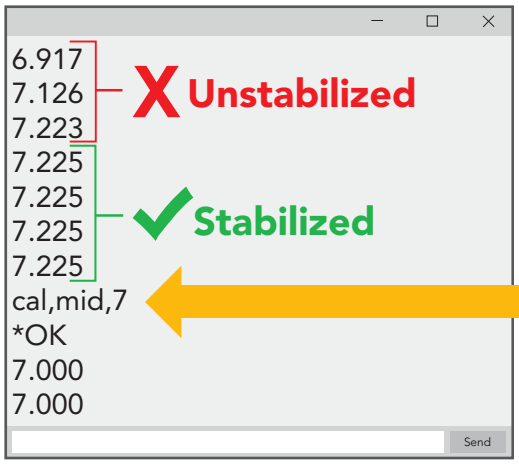
The first calibration point must be the Mid point (pH 7.00)

Mid point calibration

Remove the soaker bottle and rinse off the pH probe. Pour a small amount of the pH **7.00** calibration solution into a cup. Let the pH probe sit in the calibration solution until the readings stabilize *(small movement from one reading to the next is normal)*.



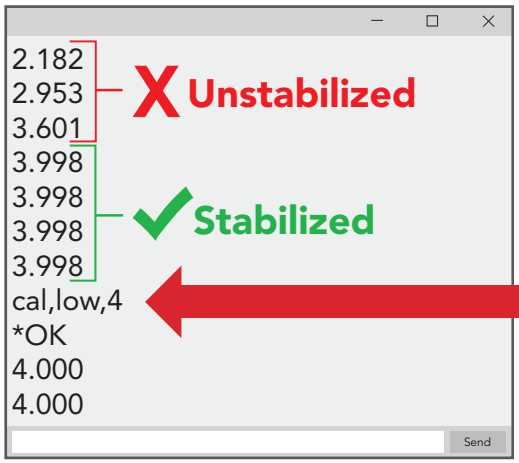




Once the readings have stabilized, issue the Mid point calibration command. **"cal,mid,7"**

Low point calibration

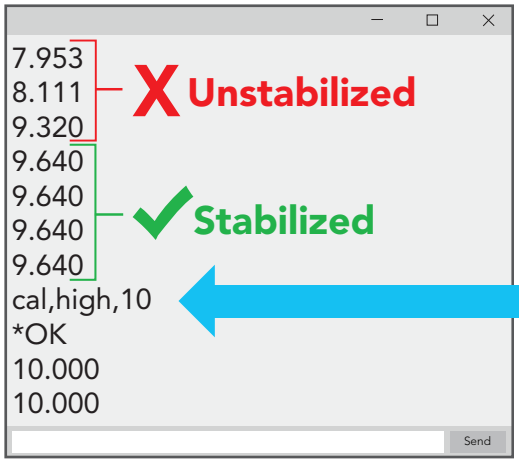
- Rinse off the probe before calibrating to the low point.
- Pour a small amount of the pH **4.00** calibration solution into a cup.
- Wait for readings to stabilize *(1 – 2 minutes)*.



Once the readings have stabilized, issue the Low point calibration command. **"cal,low,4"**

High point calibration

- Rinse off the probe before calibrating to the high point.
- Pour a small amount of the pH **10.00** calibration solution into a cup.
- Wait for readings to stabilize *(1 – 2 minutes)*.



Once the readings have stabilized, issue the High point calibration command. **"cal,high,10"**

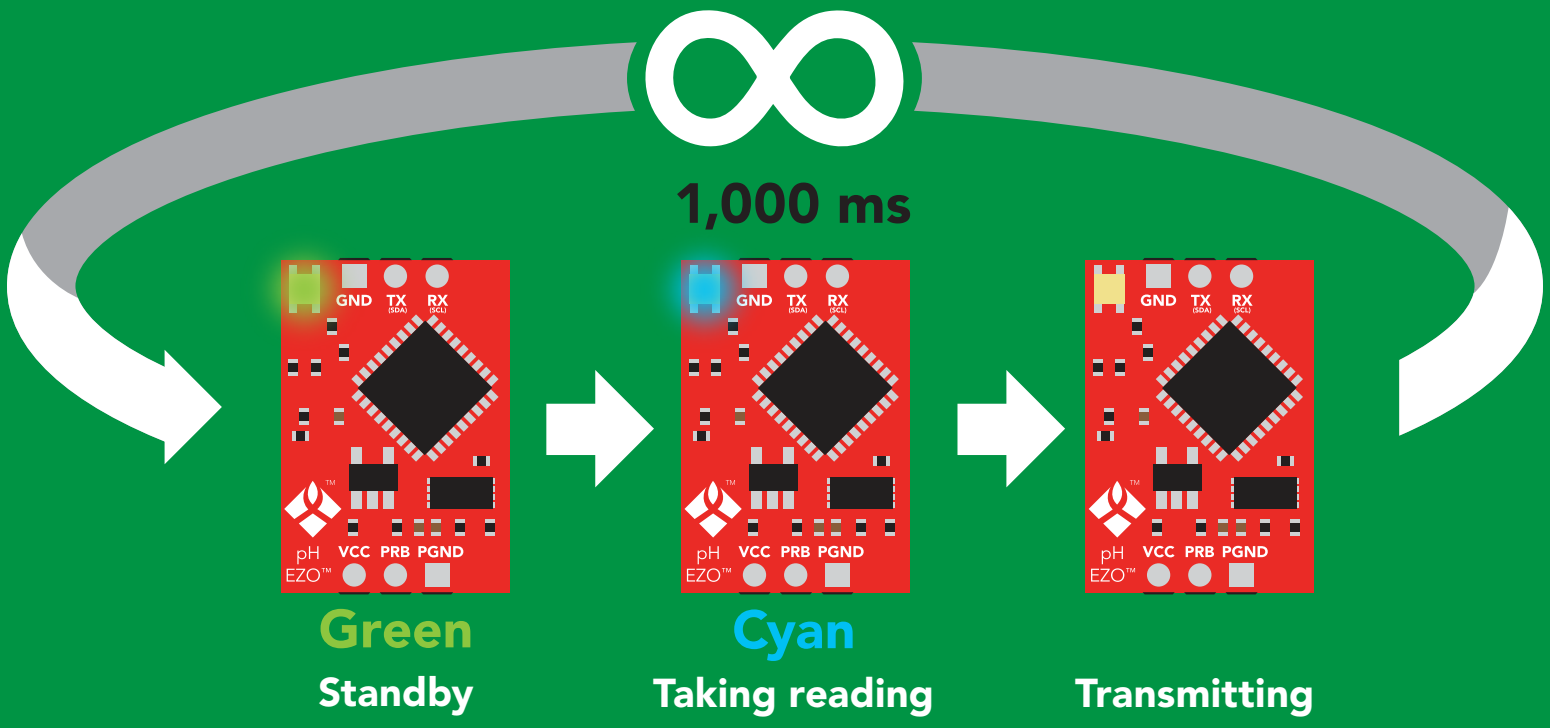
Issuing the cal,mid command after the EZO™ pH circuit has been calibrated, will clear the other calibration points. Full calibration will have to be redone.

The EZO™ pH circuits default temperature compensation is set to 25° C. If the temperature of the calibration solution is +/- 2° C from 25° C, consider setting the temperature compensation first. ***Temperature changes of < 2° C are insignificant.***

Default state

UART mode

Baud	**9,600**
Readings	**continuous**
Speed	**1 reading per second**
LED	**on**



AtlasScientific™ Environmental Robotics

✓ Available data protocols

UART

Default

I²C

X Unavailable data protocols

SPI

Analog

RS-485

Mod Bus

4–20mA

UART mode

Settings that are retained if power is cut

Baud rate
Calibration
Continuous mode
Device name
Enable/disable response codes
Hardware switch to I^2C mode
LED control
Protocol lock
Software switch to I^2C mode

Settings that are *NOT* retained if power is cut

Find
Sleep mode
Temperature compensation

Atlas Scientific™
Environmental Robotics

UART mode

8 data bits	no parity
1 stop bit	no flow control

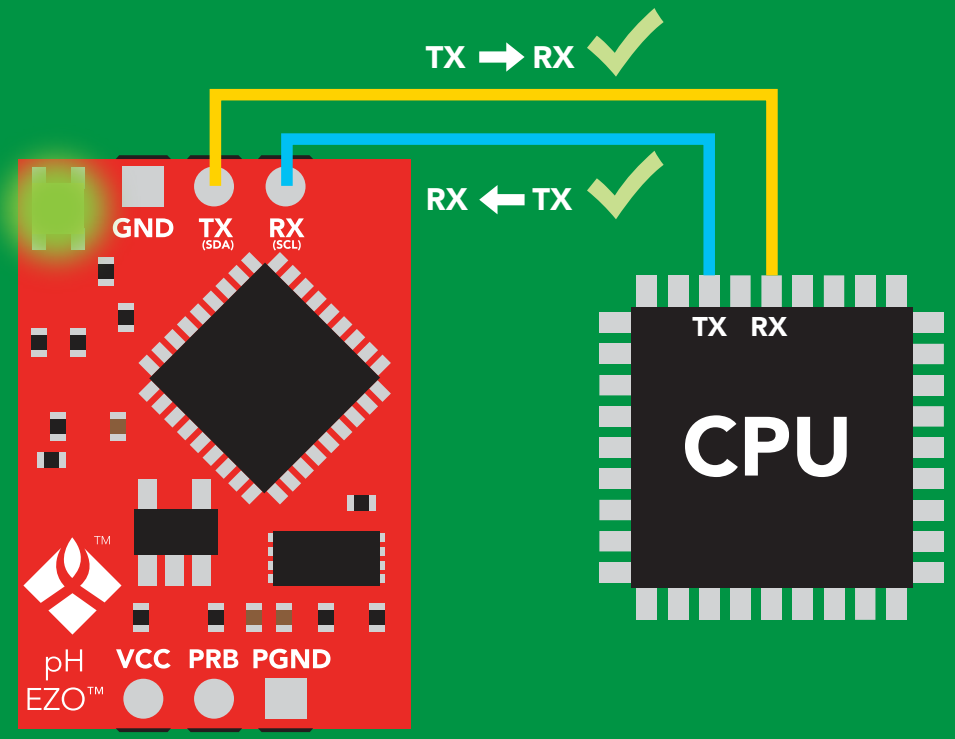
Baud

300
1,200
2,400
9,600 default
19,200
38,400
57,600
115,200

RX
Data in

TX
Data out

Vcc 3.3V – 5.5V



Data format

Reading	pH	**Data type**	floating point
Units	pH	**Decimal places**	3
Encoding	ASCII	**Smallest string**	4 characters
Format	string	**Largest string**	40 characters
Terminator	carriage return		

Receiving data from device

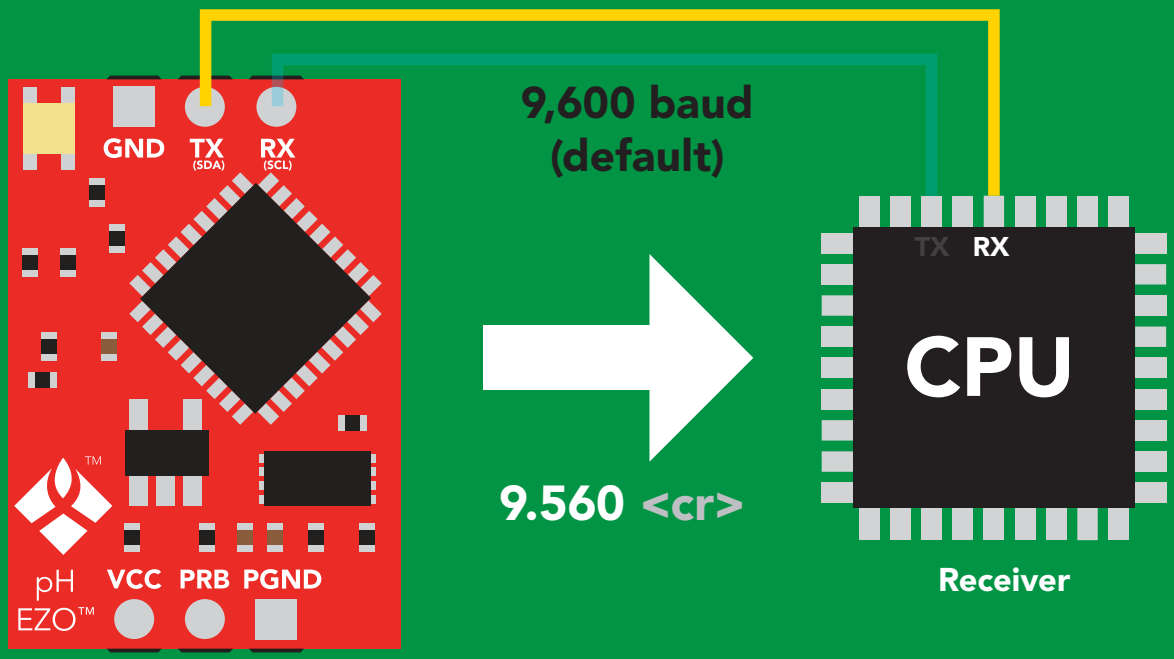
2 parts

ASCII data string

Command

Carriage return <cr>

Terminator



Sender

Receiver

Advanced

ASCII:	9	.	5	6	0	<cr>
Hex:	39	2E	35	36	30	0D
Dec:	57	46	53	54	48	13

Atlas Scientific™ Environmental Robotics

r 0.1

Sending commands to device

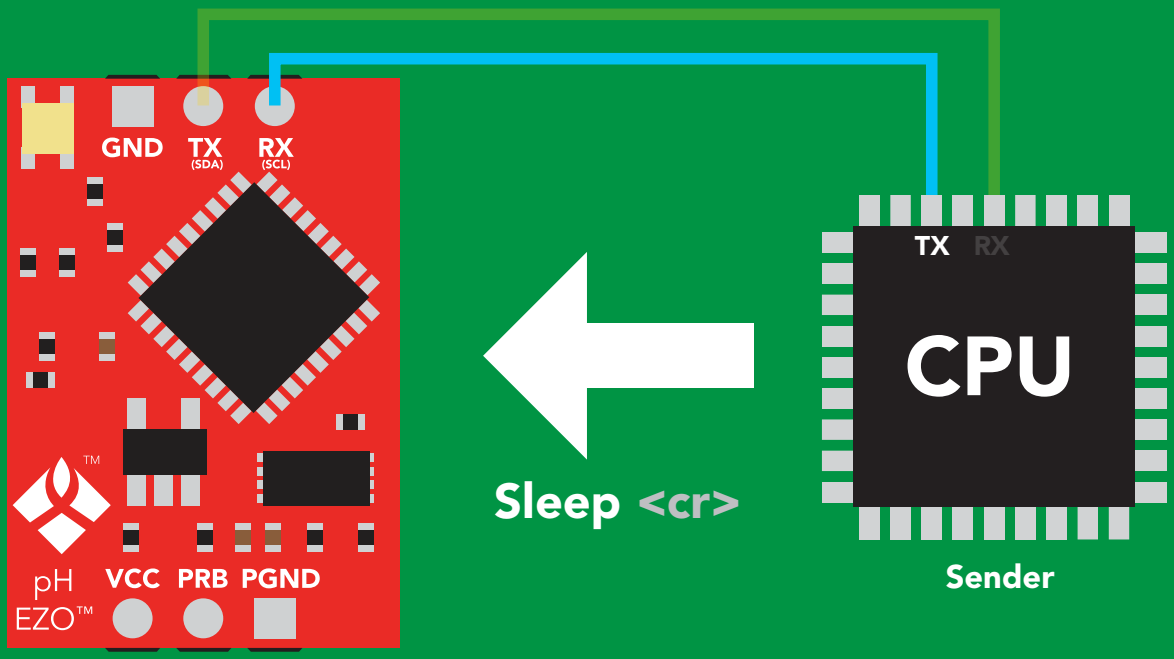
2 parts

Command (not case sensitive)

ASCII data string

Carriage return <cr>

Terminator



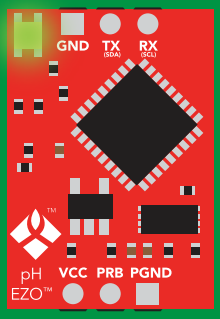
Advanced

ASCII:	S	l	e	e	p	<cr>
Hex:	53	6C	65	65	70	0D
Dec:	83	108	101	101	112	13

Atlas Scientific™ Environmental Robotics

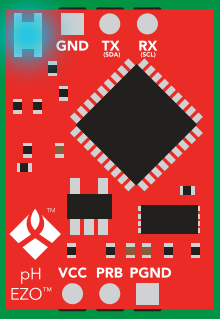
r 0.1

LED color definition



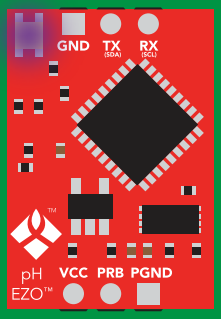
Green

UART standby



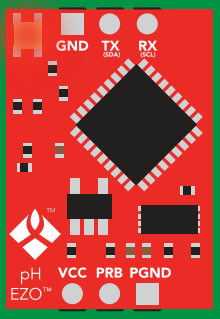
Cyan

Taking reading



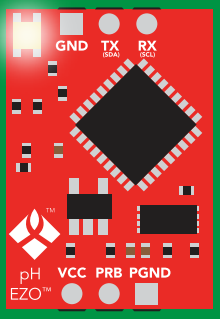
Purple

Changing baud rate



Red

Command not understood



White

Find

	LED ON
5V	**+2.2 mA**
3.3V	**+0.6 mA**

Atlas Scientific™ Environmental Robotics

r 0.1

UART mode
command quick reference

All commands are ASCII strings or single ASCII characters.

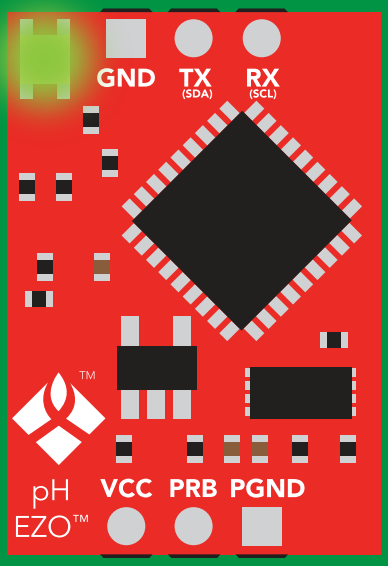
Command	Function		Default state
Baud	change baud rate	pg. 37	9,600
C	enable/disable continuous reading	pg. 24	enabled
Cal	performs calibration	pg. 26	n/a
Export	export calibration	pg. 27	n/a
Factory	enable factory reset	pg. 39	n/a
Find	finds device with blinking white LED	pg. 23	n/a
i	device information	pg. 33	n/a
I2C	change to I²C mode	pg. 40	not set
Import	import calibration	pg. 28	n/a
L	enable/disable LED	pg. 22	enabled
Name	set/show name of device	pg. 32	not set
pHext	enable/disable extended pH scale	pg. 30	disabled
Plock	enable/disable protocol lock	pg. 38	disabled
R	returns a single reading	pg. 25	n/a
Sleep	enter sleep mode/low power	pg. 36	n/a
Slope	returns the slope of the pH probe	pg. 29	n/a
Status	retrieve status information	pg. 35	enable
T	temperature compensation	pg. 31	25˚C
*OK	enable/disable response codes	pg. 34	enable

LED control

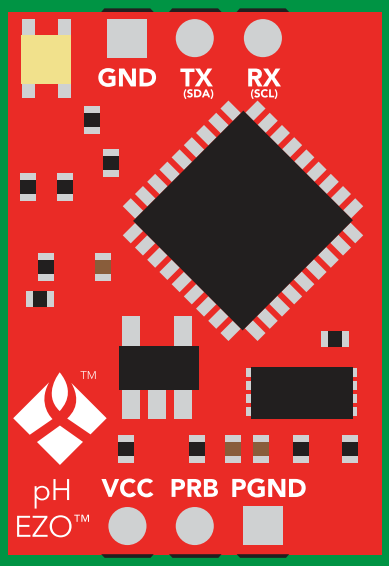
Command syntax

L,1 <cr> LED on **default**
L,0 <cr> LED off
L,? <cr> LED state on/off?

Example	Response
L,1 <cr>	*OK <cr>
L,0 <cr>	*OK <cr>
L,? <cr>	?L,1 <cr> or ?L,0 <cr> *OK <cr>



L,1



L,0

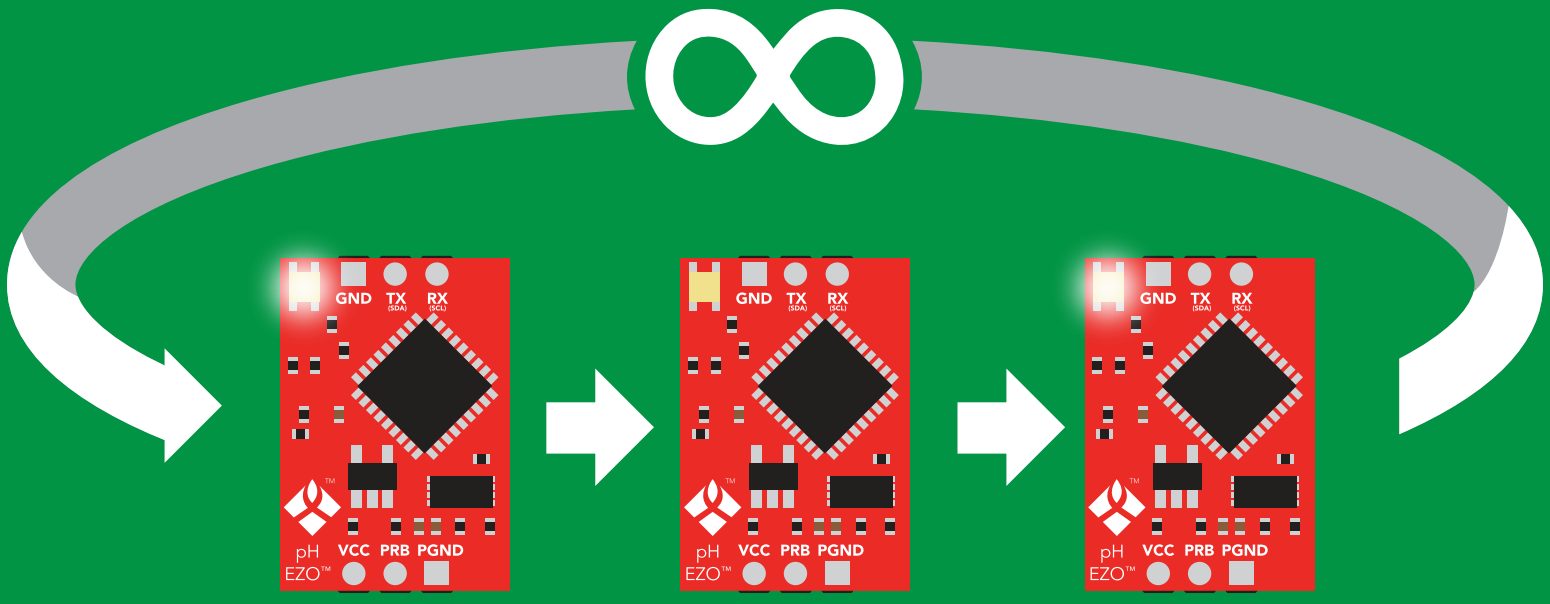
Find

Command syntax

This command will disable continuous mode
Send any character or command to terminate find.

Find <cr> **LED rapidly blinks white, used to help find device**

Example	Response
Find <cr>	***OK** <cr>



AtlasScientific™
Environmental Robotics
r 0.1

Continuous reading mode

Command syntax

C,1 <cr> enable continuous readings once per second **default**

C,n <cr> continuous readings every n seconds (n = 2 to 99 sec)

C,0 <cr> disable continuous readings

C,? <cr> continuous reading mode on/off?

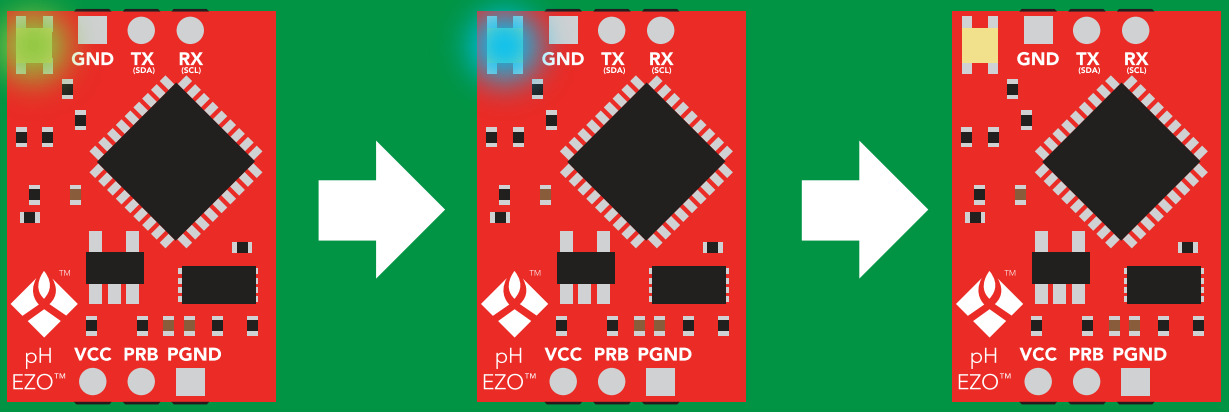
Example	Response
C,1 <cr>	*OK <cr> pH (1 sec) <cr> pH (2 sec) <cr> pH (n sec) <cr>
C,30 <cr>	*OK <cr> pH (30 sec) <cr> pH (60 sec) <cr> pH (90 sec) <cr>
C,0 <cr>	*OK <cr>
C,? <cr>	?C,1 <cr> or ?C,0 <cr> or ?C,30 <cr> *OK <cr>

Single reading mode

Command syntax

R <cr> takes single reading

Example	Response
R <cr>	9.560 <cr> *OK <cr>



Green
Standby

Cyan
Taking reading

Transmitting

800 ms

Calibration

Command syntax

Issuing the cal,mid command after the EZO™ pH circuit has been calibrated, will clear the other calibration points. Full calibration will have to be redone.

Cal,mid,n	<cr>	single point calibration at midpoint
Cal,low,n	<cr>	two point calibration at lowpoint
Cal,high,n	<cr>	three point calibration at highpoint
Cal,clear	<cr>	delete calibration data
Cal,?	<cr>	device calibrated?

Example	Response
Cal,mid,7.00 <cr>	*OK <cr>
Cal,low,4.00 <cr>	*OK <cr>
Cal,high,10.00 <cr>	*OK <cr>
Cal,clear <cr>	*OK <cr>
Cal,? <cr>	?Cal,0 <cr> or ?Cal,1 <cr> (one point) or ?Cal,2 <cr> (two point) or ?Cal,3 <cr> (three point) *OK <cr>

Export calibration

Command syntax

Export: Use this command to download calibration settings

Export,?	<cr>	calibration string info
Export	<cr>	export calibration string from calibrated device

Example

Response

Export,? <cr>

10,120 <cr>

Response breakdown

10, 120

↑ # of strings to export

↑ # of bytes to export

Export strings can be up to 12 characters long, and is always followed by <cr>

Export <cr>

59 6F 75 20 61 72 <cr> (1 of 10)

Export <cr>

65 20 61 20 63 6F <cr> (2 of 10)

(7 more)

⋮

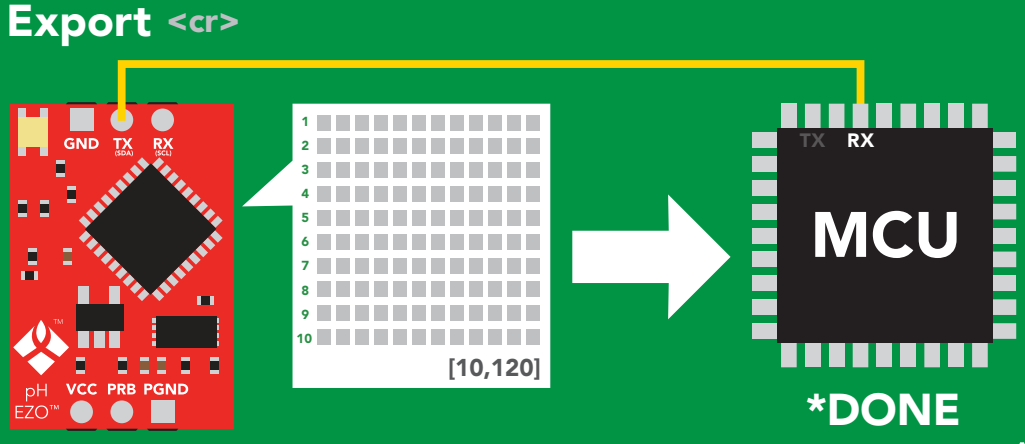
Export <cr>

6F 6C 20 67 75 79 <cr> (10 of 10)

Export <cr>

***DONE**

Disabling *OK simplifies this process



Atlas Scientific™ Environmental Robotics

r 0.2

Import calibration

Command syntax

Import: Use this command to upload calibration settings to one or more devices.

Import,n <cr> import calibration string to new device

Example

Import, 59 6F 75 20 61 72 <cr> (1 of 10)

Import, 65 20 61 20 63 6F <cr> (2 of 10)

⋮

Import, 6F 6C 20 67 75 79 <cr> (10 of 10)

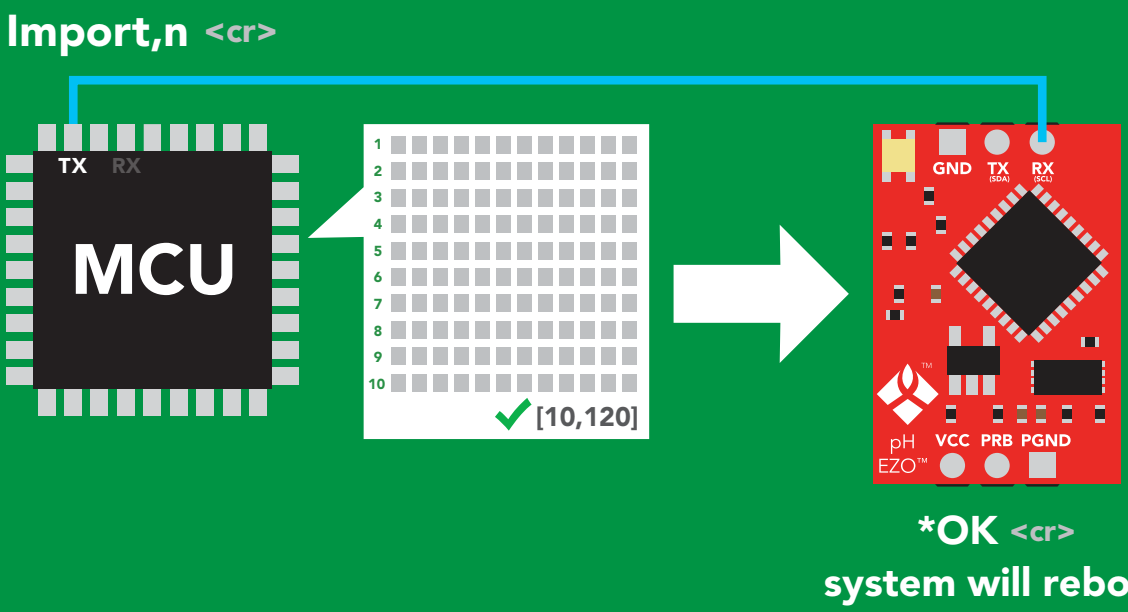
Response

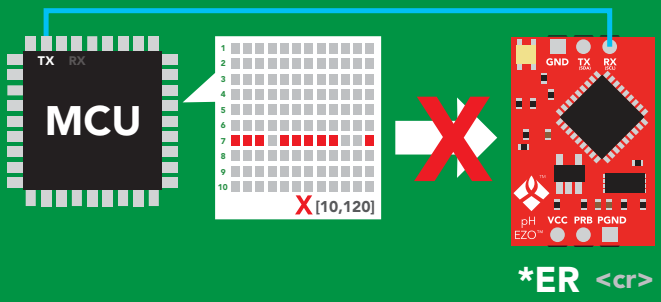
*OK <cr>

*OK <cr>

⋮

*OK <cr>





*** If one of the imported strings is not correctly entered, the device will not accept the import, respond with *ER and reboot.**

Atlas Scientific™ Environmental Robotics

r 0.2

Slope

Command syntax

After calibrating a pH probe issuing the slope command will show how closely (in percentage) the calibrated pH probe is working compared to the "ideal" pH probe.

Slope,? <cr> returns the slope of the pH probe

Example	Response
Slope,? <cr>	?Slope,99.7,100.3, -0.89 <cr> *OK <cr>

Response breakdown

?Slope,

99.7

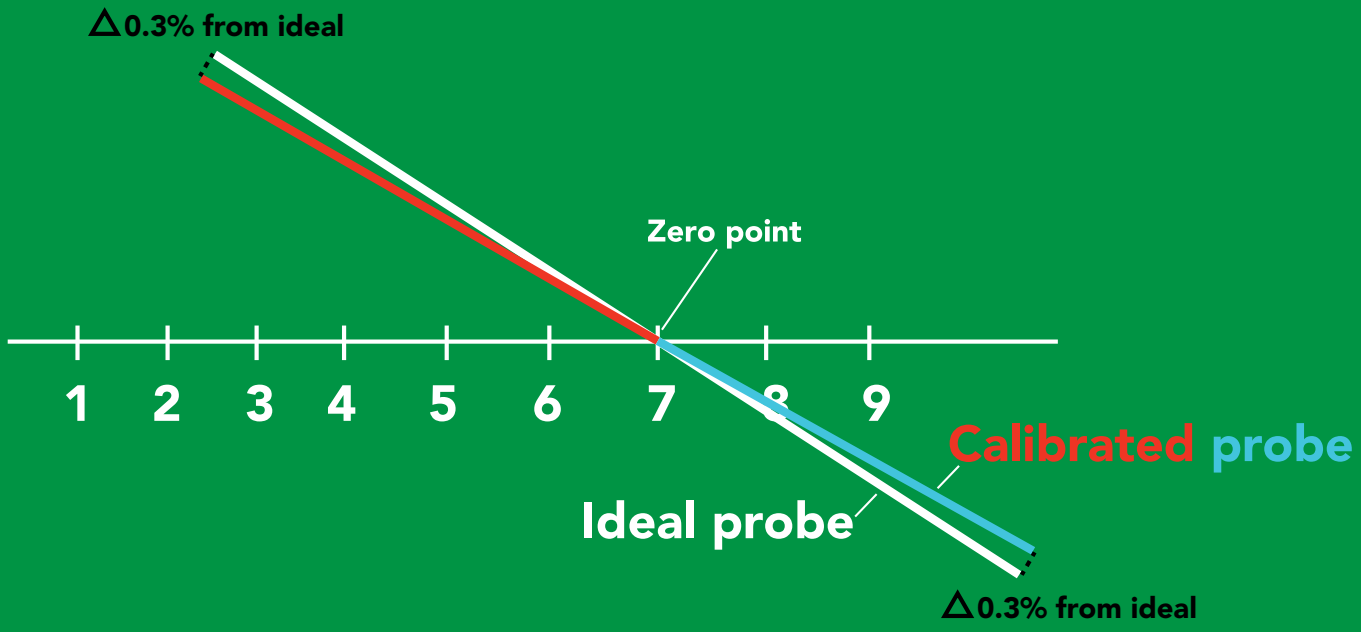
99.7% is how closely the slope of the **acid** calibration line matched the "ideal" pH probe.

100.3

100.3% is how closely the slope of the **base** calibration matches the "ideal" pH probe.

-0.89

This is how many millivolts the zero point is off from true 0.



Extended pH scale

Very strong acids and basses can exceed the traditional pH scale. This command extends the pH scale to show below 0 and above 14.

Lowest possible reading: **-1.6**
Highest possible reading: **15.6**

Command syntax

pHext,0 <cr>	extended pH scale off (0–14)	**default**
pHext,1 <cr>	extended pH scale on (-1.6–15.6)	
pHext,? <cr>	extended pH scale on/off?	

Example	Response
pHext,1 <cr>	*OK <cr>
pHext,0 <cr>	*OK <cr>
pHext,? <cr>	?pHext,1 <cr> **or** ?pHext,0 <cr>

pHext,0

pH = 0.000

pHext,1

pH = -1.220

Temperature compensation

Command syntax

Default temperature = 25°C
Temperature is always in Celsius
Temperature is not retained if power is cut

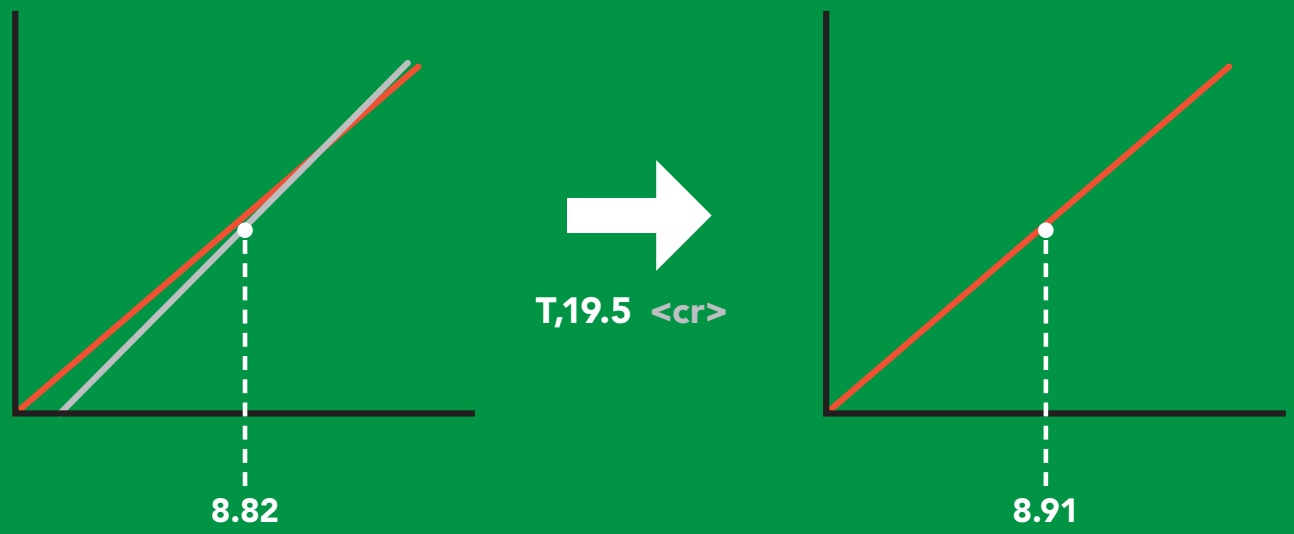
T,n <cr> n = any value; floating point or int

T,? <cr> compensated temperature value?

RT,n <cr> set temperature compensation and take a reading*

This is a new command for firmware V2.12

Example	Response
T,19.5 <cr>	*OK <cr>
RT,19.5 <cr>	*OK <cr> 8.91 <cr>
T,? <cr>	?T,19.5 <cr> *OK <cr>



AtlasScientific™
Environmental Robotics
r 0.2

Naming device

Command syntax

Do not use spaces in the name

Name,n <cr> set name

Name,? <cr> show name

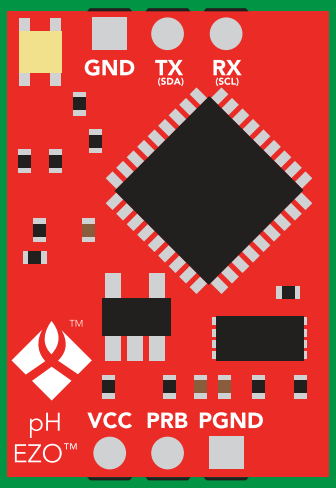
n = _ _ _ _ _ _ _ _ _ _ _ _ _ _ _ _

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16

Up to 16 ASCII characters

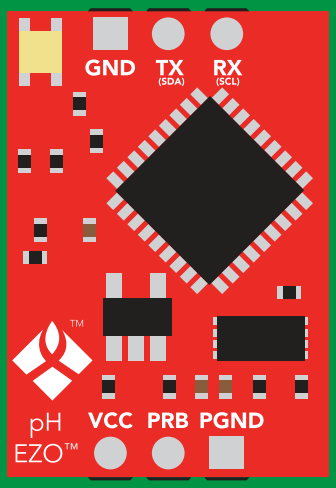
Example	Response
Name,zzt <cr>	*OK <cr>
Name,? <cr>	?Name,zzt <cr> *OK <cr>

Name,zzt



*OK <cr>

Name,?



Name,zzt <cr>
*OK <cr>

Device information

Command syntax

i <cr> **device information**

Example	Response
i <cr>	?i,pH,1.98 <cr> *OK <cr>

Response breakdown

?i,	pH,	1.98
	↑ Device	↑ Firmware

Response codes

Command syntax

*OK,1 <cr> enable response **default**
*OK,0 <cr> disable response
*OK,? <cr> response on/off?

Example	Response
R <cr>	9.560 <cr> *OK <cr>
*OK,0 <cr>	no response, *OK disabled
R <cr>	9.560 <cr> *OK disabled
*OK,? <cr>	?*OK,1 <cr> or ?*OK,0 <cr>

Other response codes

*ER	unknown command
*OV	over volt (VCC>=5.5V)
*UV	under volt (VCC<=3.1V)
*RS	reset
*RE	boot up complete, ready
*SL	entering sleep mode
*WA	wake up

These response codes cannot be disabled

Reading device status

Command syntax

Status <cr> **voltage at Vcc pin and reason for last restart**

Example	Response
Status <cr>	**?Status,P,5.038** <cr> ***OK** <cr>

Response breakdown

?Status, P, 5.038

- **P** — Reason for restart
- **5.038** — Voltage at Vcc

Restart codes

P	powered off
S	software reset
B	brown out
W	watchdog
U	unknown

Sleep mode/low power

Command syntax

Send any character or command to awaken device.

Sleep <cr> enter sleep mode/low power

Example	Response
Sleep <cr>	*OK <cr> *SL <cr>
Any command	*WA <cr> wakes up device

	STANDBY	SLEEP
5V	16 mA	1.16 mA
3.3V	13.9 mA	0.995 mA

Standby
16 mA

Sleep
1.16 mA

Atlas Scientific™ Environmental Robotics

r 0.1

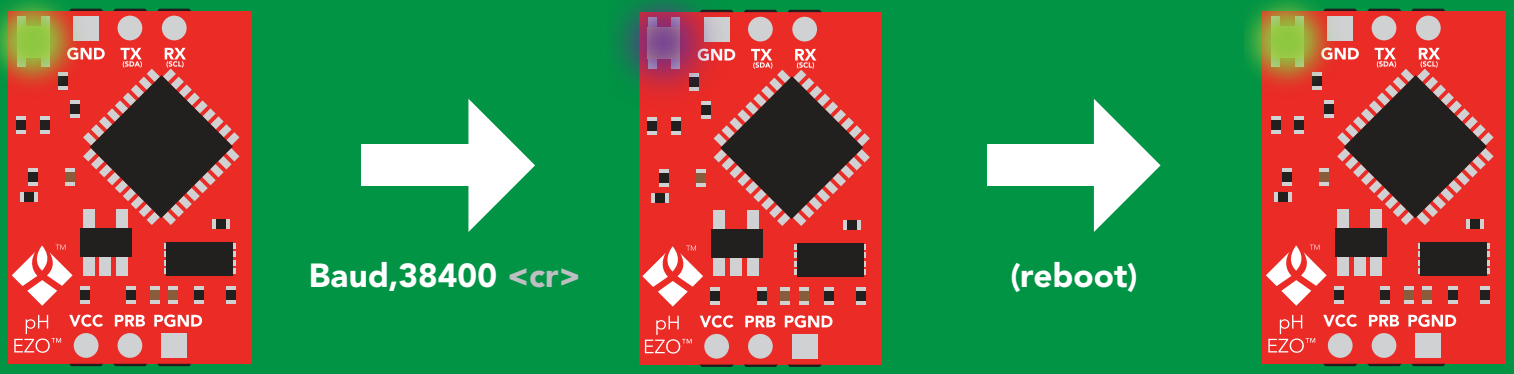
Change baud rate

Command syntax

Baud,n <cr> change baud rate

Example	Response
Baud,38400 <cr>	*OK <cr>
Baud,? <cr>	?Baud,38400 <cr> *OK <cr>

n =
- 300
- 1200
- 2400
- **9600 default**
- 19200
- 38400
- 57600
- 115200



Standby

Changing baud rate

*OK <cr>

Standby

Atlas Scientific™ Environmental Robotics

r 0.1

Protocol lock

Command syntax

Locks device to UART mode.

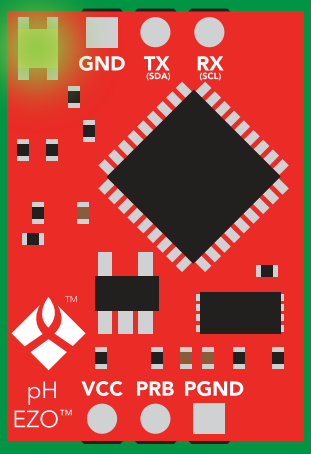
Plock,1 <cr> enable Plock

Plock,0 <cr> disable Plock **default**

Plock,? <cr> Plock on/off?

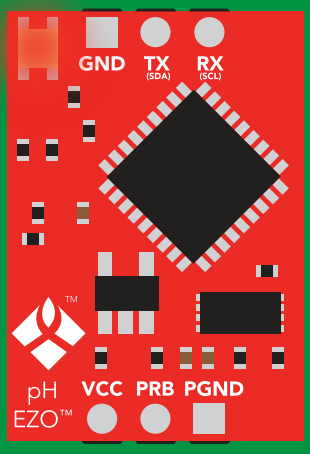
Example	Response
Plock,1 <cr>	*OK <cr>
Plock,0 <cr>	*OK <cr>
Plock,? <cr>	?Plock,1 <cr> or ?Plock,0 <cr>

Plock,1



*OK <cr>

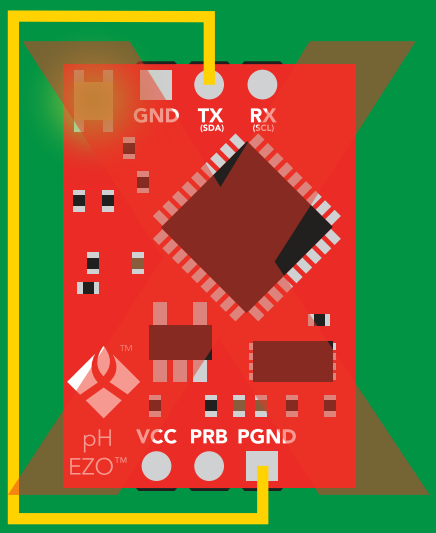
I2C,100



cannot change to I²C

*ER <cr>

Short



cannot change to I²C

AtlasScientific™ Environmental Robotics

r 0.1

Factory reset

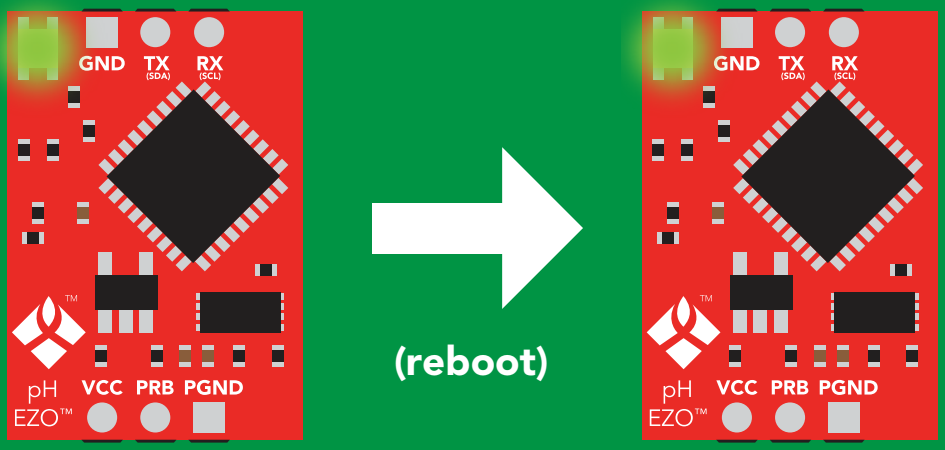
Command syntax

Clears calibration LED on "*OK" enabled

Factory <cr> enable factory reset

Example	Response
Factory <cr>	***OK** <cr>

Factory <cr>



***OK** <cr>

***RS** <cr>
***RE** <cr>

Baud rate will not change

Atlas Scientific™ Environmental Robotics

r 0.1

Change to I²C mode

Command syntax

Default I²C address 99 (0x63)

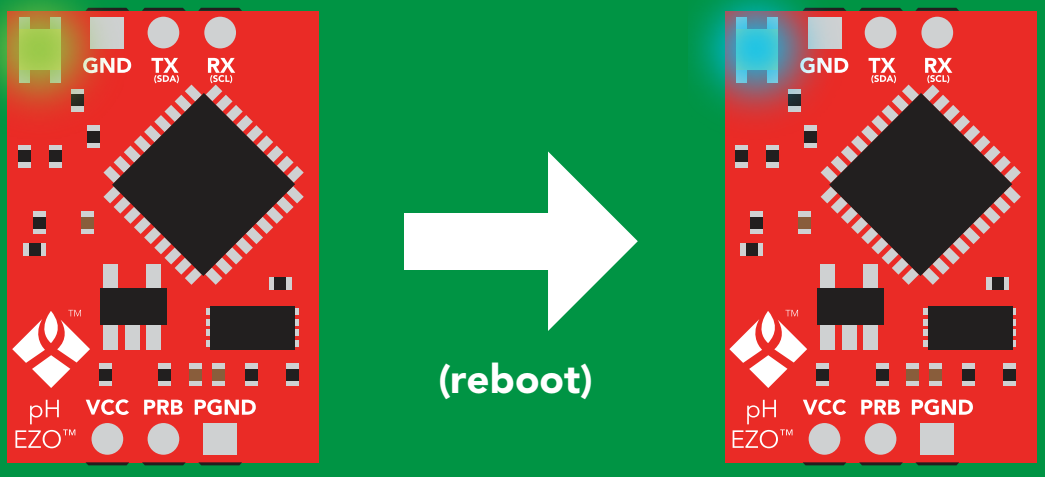
I2C,n <cr> sets I²C address and reboots into I²C mode

n = any number 1 – 127

Example	Response
I2C,100 <cr>	*OK (reboot in I²C mode)

Wrong example	Response
I2C,139 <cr> n ≯ 127	*ER <cr>

I2C,100



Green
*OK <cr>

Blue
now in I²C mode

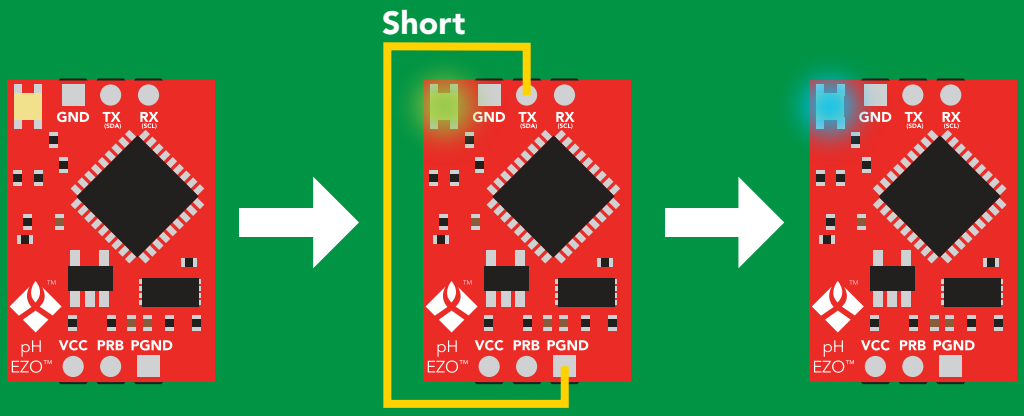
Atlas Scientific™ Environmental Robotics
r 0.2

Manual switching to I²C

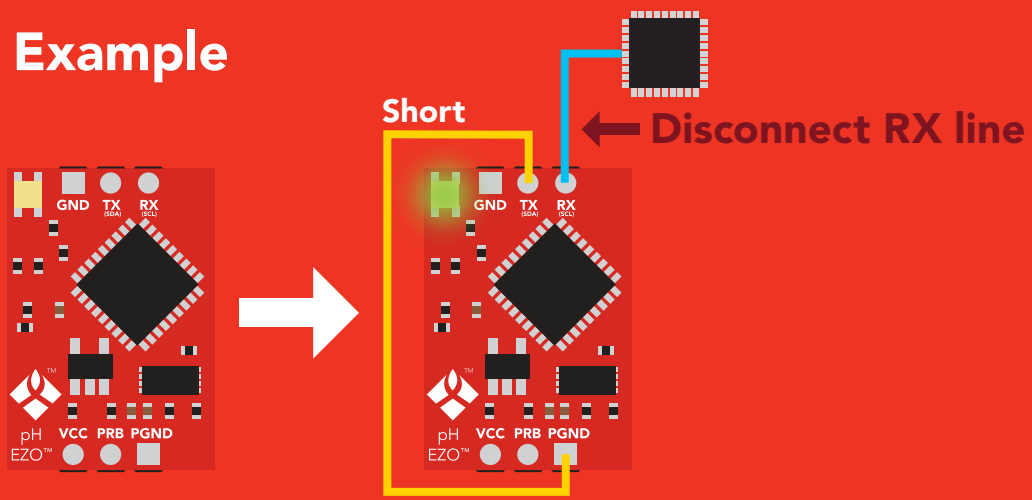
- Disconnect ground (power off)
- Disconnect TX and RX
- Connect TX to PGND
- Confirm RX is disconnected
- Connect ground (power on)
- Wait for LED to change from Green to Blue
- Disconnect ground (power off)
- Reconnect all data and power

Manually switching to I²C will set the I²C address to 99 (0x63)

Example



Wrong Example



I²C mode

The I²C protocol is *considerably more complex* than the UART (RS–232) protocol. Atlas Scientific assumes the embedded systems engineer understands this protocol.

To set your EZO™ device into I²C mode click here

Settings that are retained if power is cut

Calibration
Change I²C address
Hardware switch to UART mode
LED control
Protocol lock
Software switch to UART mode

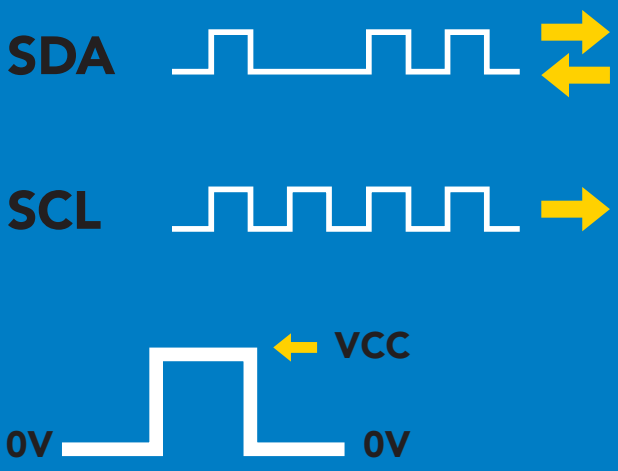
Settings that are *NOT* retained if power is cut

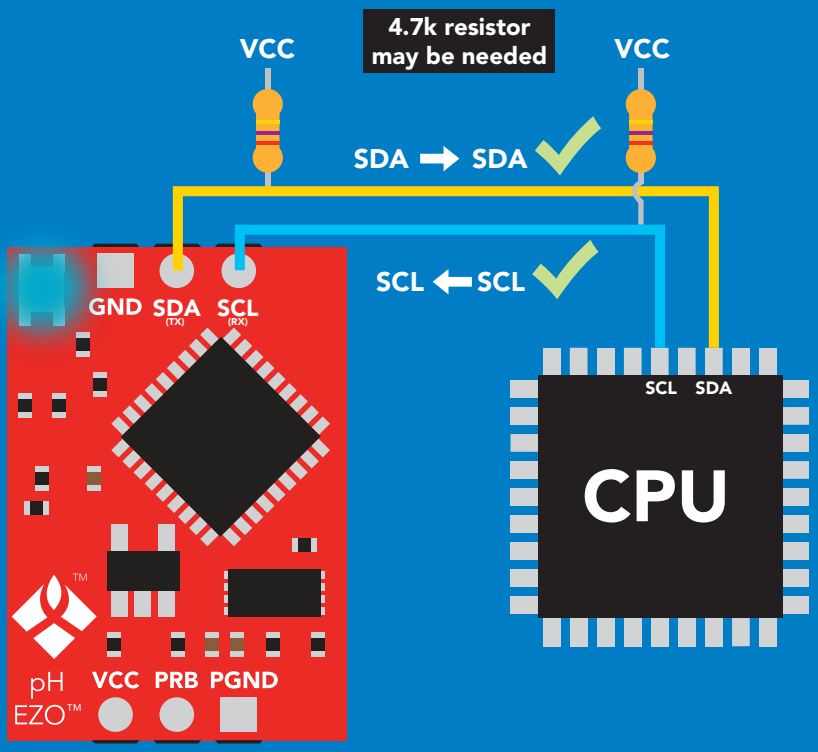
Find
Sleep mode
Temperature compensation

Atlas Scientific™
Environmental Robotics

I²C mode

I²C address	(0x01 – 0x7F) **99 (0x63) default**
Vcc	3.3V – 5.5V
Clock speed	100 – 400 kHz





Data format

Reading	pH	Data type	floating point
Units	pH	Decimal places	3
Encoding	ASCII	Smallest string	4 characters
Format	string	Largest string	40 characters

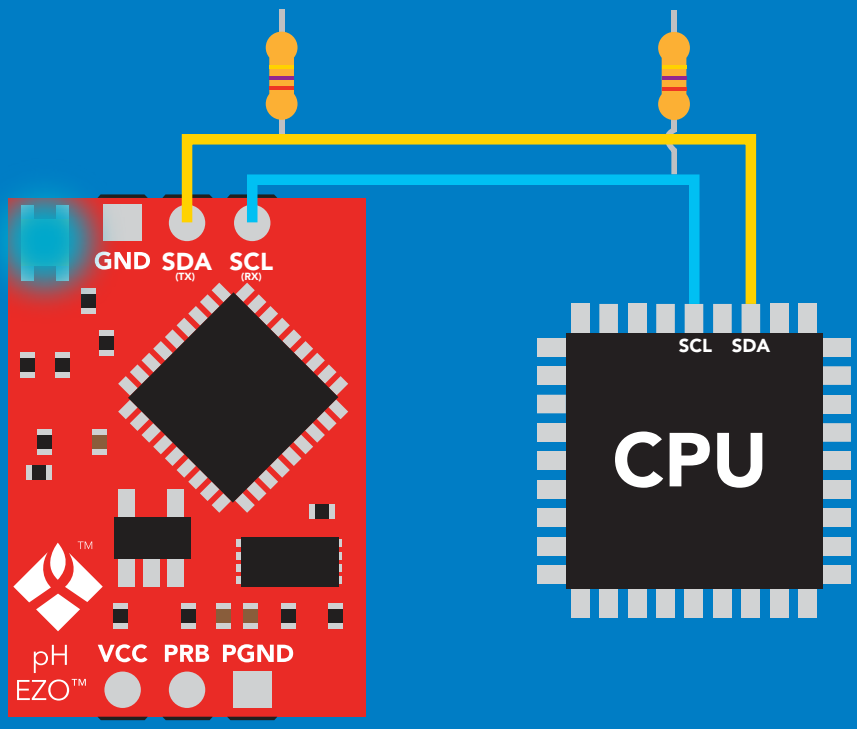
Sending commands to device

5 parts

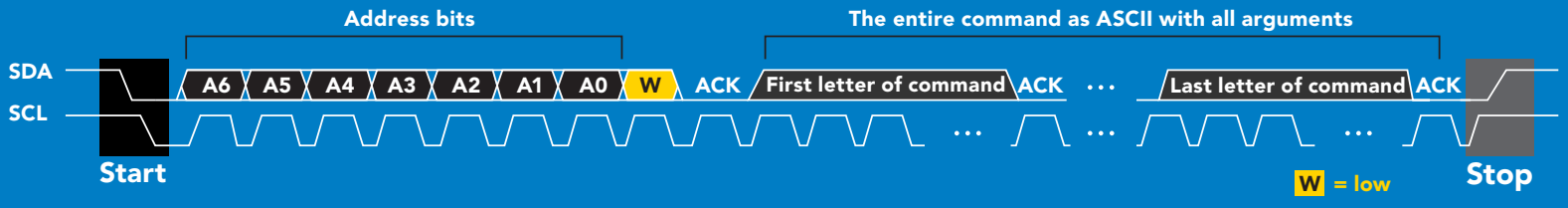
Start	I²C address	Write	Command (not case sensitive)	Stop
	99 (0x63)		ASCII command string	

Example

Start	99 (0x63)	Write	Sleep	Stop
	I²C address		Command	

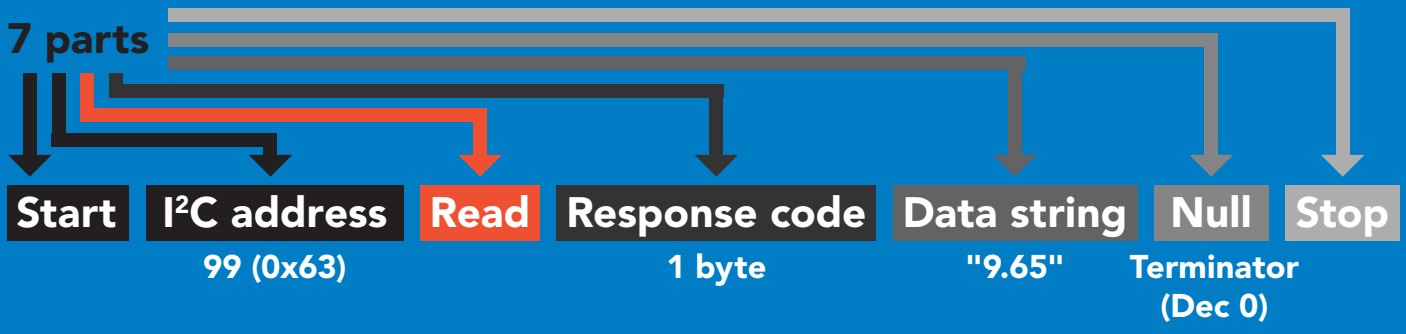


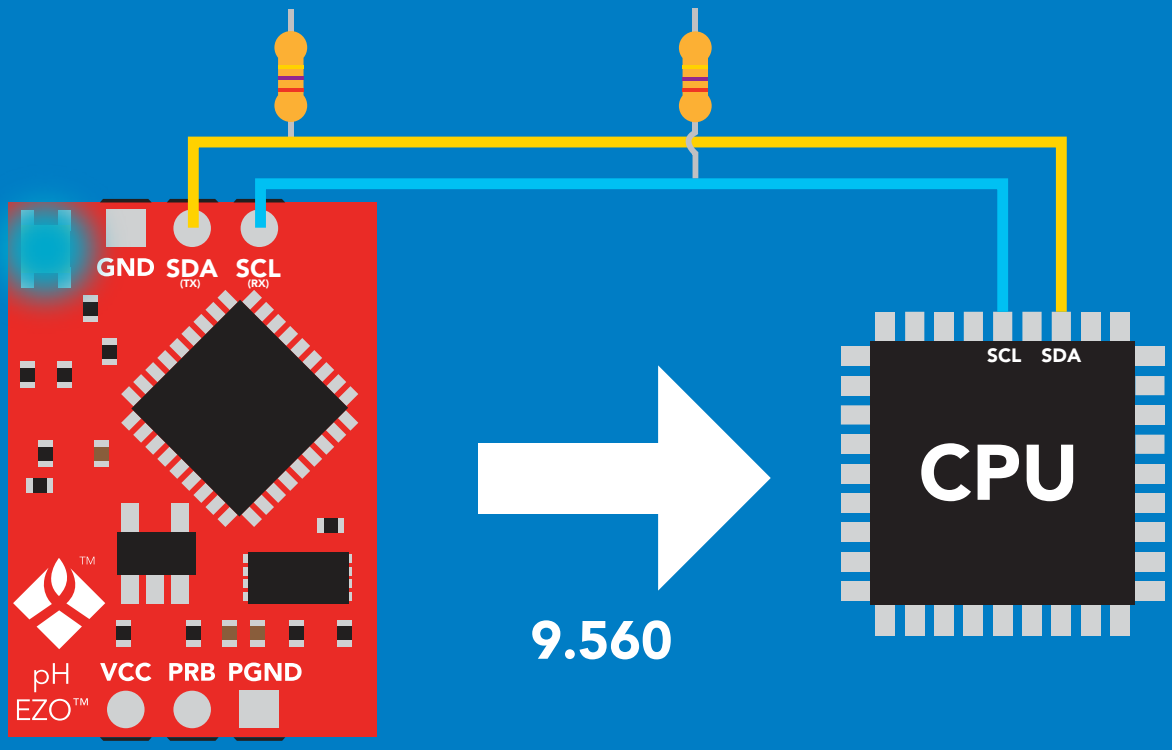
Advanced



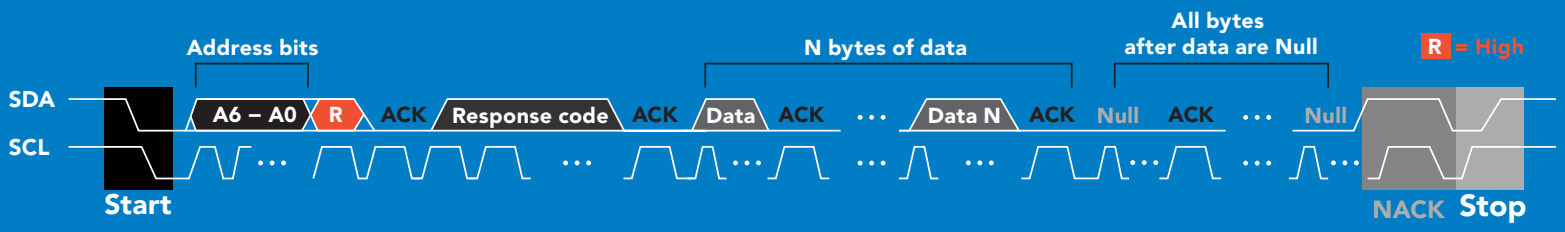
AtlasScientific™
Environmental Robotics
r 0.1

Requesting data from device





Advanced

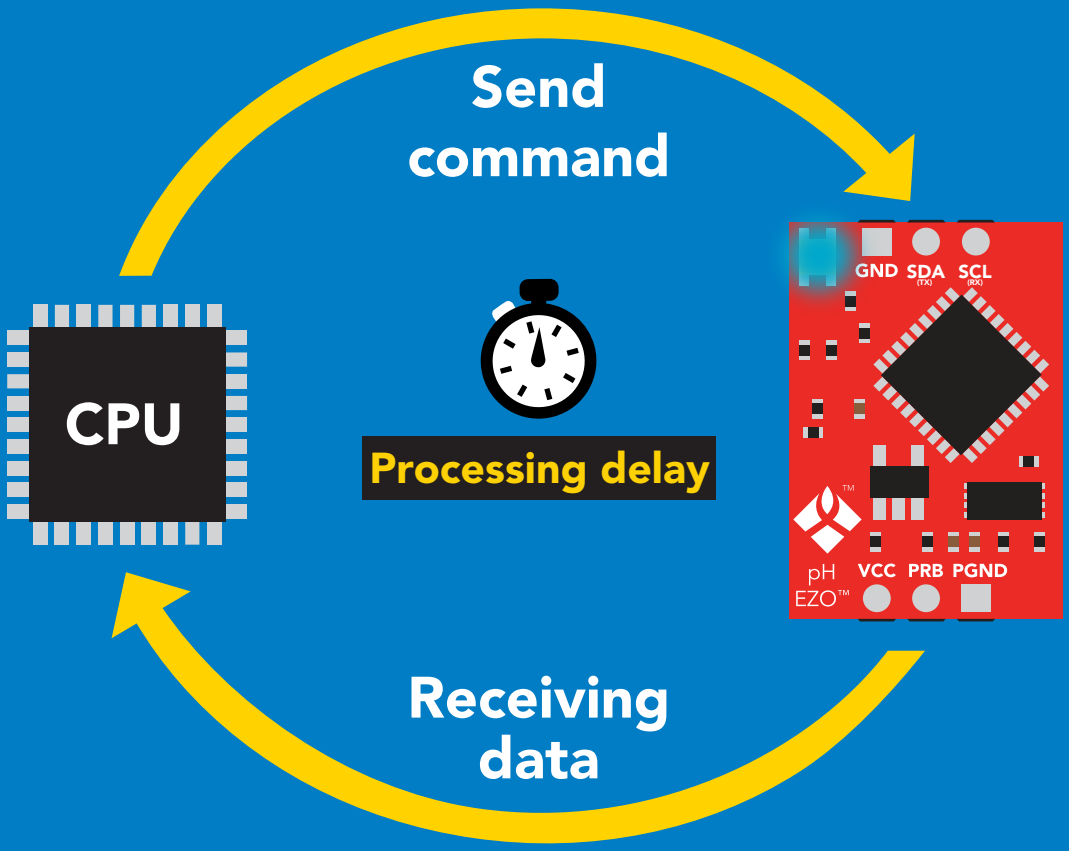


AtlasScientific™
Environmental Robotics
r 0.1

Response codes

After a command has been issued, a 1 byte response code can be read in order to confirm that the command was processed successfully.

Reading back the response code is completely optional, and is not required for normal operation.



Example

```
I2C_start;
I2C_address;
I2C_write(EZO_command);
I2C_stop;
```

```
delay(300);
```

Processing delay

```
I2C_start;
I2C_address;
Char[ ] = I2C_read;
I2C_stop;
```

If there is no processing delay or the processing delay is too short, the response code will always be 254.

Response codes

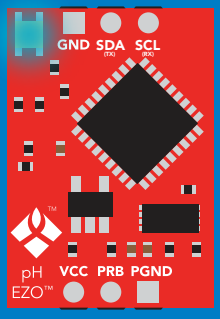
Single byte, not string

255	no data to send
254	still processing, not ready
2	syntax error
1	successful request

AtlasScientific™ Environmental Robotics

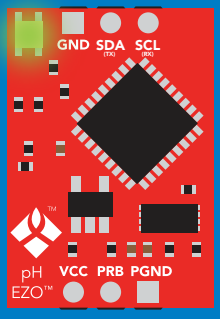
r 0.2

LED color definition



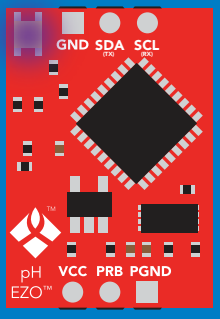
Blue

I²C standby



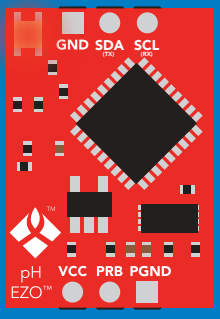
Green

Taking reading



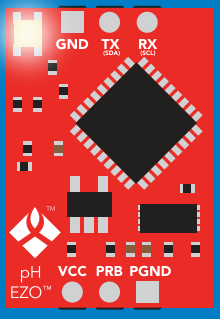
Purple

Changing I²C address



Red

Command not understood



White

Find

	LED ON
5V	**+2.2 mA**
3.3V	**+0.6 mA**

I²C mode
command quick reference

All commands are ASCII strings or single ASCII characters.

Command	Function	
Baud	switch back to UART mode	pg. 65
Cal	performs calibration	pg. 52
Export	export calibration	pg. 53
Factory	enable factory reset	pg. 64
Find	finds device with blinking white LED	pg. 50
i	device information	pg. 59
I2C	change I²C address	pg. 63
Import	import calibration	pg. 54
L	enable/disable LED	pg. 49
Name	set/show name of device	pg. 58
pHext	enable/disable extended pH scale	pg. 56
Plock	enable/disable protocol lock	pg. 62
R	returns a single reading	pg. 51
Sleep	enter sleep mode/low power	pg. 61
Slope	returns the slope of the pH probe	pg. 55
Status	retrieve status information	pg. 60
T	temperature compensation	pg. 57

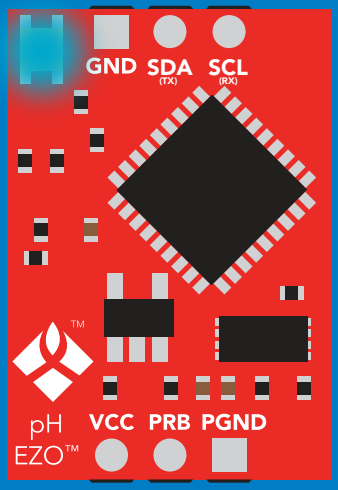
LED control

Command syntax

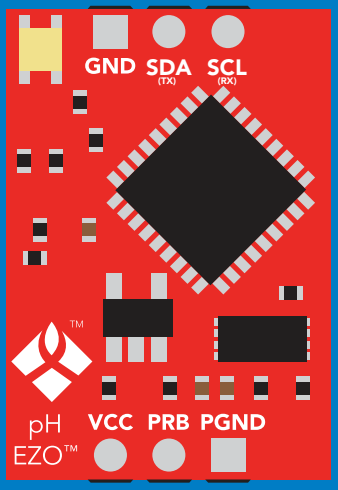
300ms processing delay

L,1	LED on	default
L,0	LED off	
L,?	LED state on/off?	

Example	Response
L,1	Wait 300ms — 1 (Dec) 0 (Null)
L,0	Wait 300ms — 1 (Dec) 0 (Null)
L,?	Wait 300ms — 1 (Dec) ?L,1 (ASCII) 0 (Null) or 1 (Dec) ?L,0 (ASCII) 0 (Null)



L,1



L,0

Atlas Scientific™ Environmental Robotics

r 0.1

Find

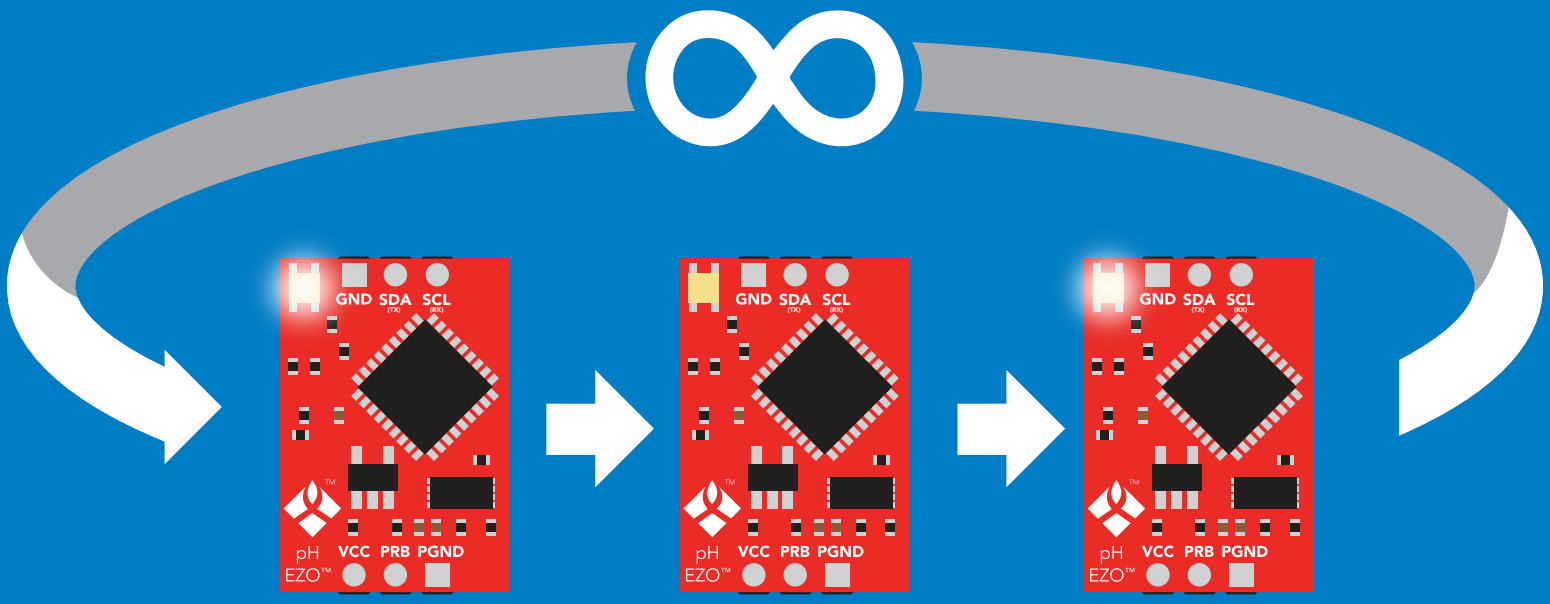
300ms processing delay

Command syntax

This command will disable continuous mode
Send any character or command to terminate find.

Find	LED rapidly blinks white, used to help find device

Example	Response
Find	Wait 300ms 1 Dec 0 Null



Atlas Scientific Environmental Robotics

r 0.1

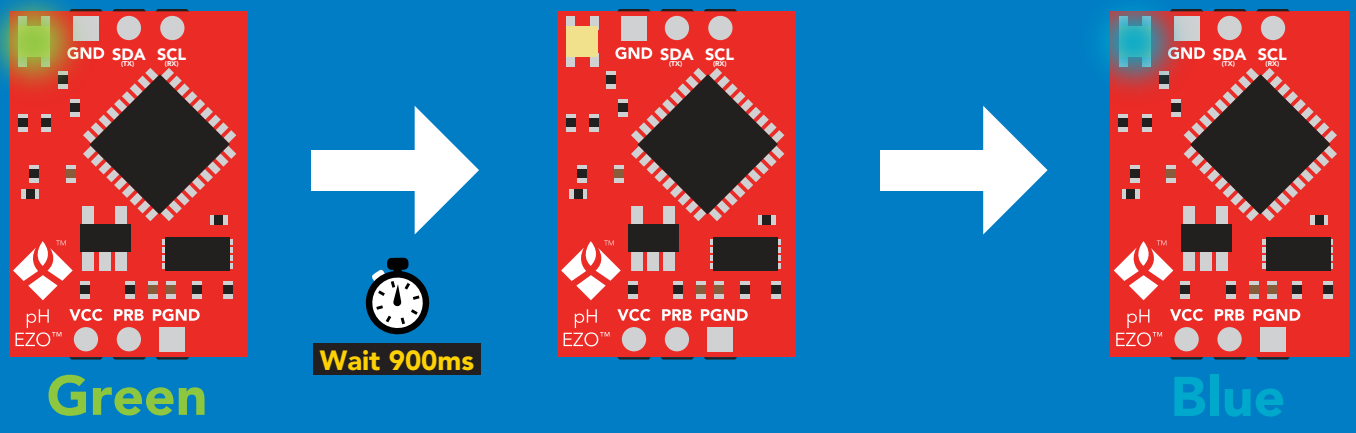
Taking reading

Command syntax

900ms processing delay

R return 1 reading

Example	Response
R	Wait 900ms 1 Dec 9.560 ASCII 0 Null



Calibration

900ms processing delay

Issuing the cal,mid command after the EZO™ pH circuit has been calibrated, will clear the other calibration points. Full calibration will have to be redone.

Command syntax

Cal,mid,n	single point calibration at midpoint
Cal,low,n	two point calibration at lowpoint
Cal,high,n	three point calibration at highpoint
Cal,clear	delete calibration data
Cal,?	device calibrated?

Example	Response
Cal,mid,7.00	Wait 900ms → 1 (Dec) 0 (Null)
Cal,low,4.00	Wait 900ms → 1 (Dec) 0 (Null)
Cal,high,10.00	Wait 900ms → 1 (Dec) 0 (Null)
Cal,clear	Wait 300ms → 1 (Dec) 0 (Null)
Cal,?	Wait 300ms → 1 (Dec) ?Cal,0 (ASCII) 0 (Null) or 1 (Dec) ?Cal,1 (ASCII one point) 0 (Null) 1 (Dec) ?Cal,2 (ASCII two point) 0 (Null) or 1 (Dec) ?Cal,3 (ASCII three point) 0 (Null)

Atlas Scientific™ Environmental Robotics

Export calibration

300ms processing delay

Command syntax

Export: Use this command to download calibration settings

Export,?	calibration string info
Export	export calibration string from calibrated device

Example

Response

Export,?

1	10,120	0
Dec	ASCII	Null

Response breakdown

10, 120

# of strings to export — # of bytes to export

Export strings can be up to 12 characters long

Export

1	59 6F 75 20 61 72	0
Dec	ASCII	Null

(1 of 10)

Export

1	65 20 61 20 63 6F	0
Dec	ASCII	Null

(2 of 10)

(7 more)

⋮

Export

1	6F 6C 20 67 75 79	0
Dec	ASCII	Null

(10 of 10)

Export

1	*DONE	0
Dec	ASCII	Null

Atlas Scientific™ Environmental Robotics

r 0.2

Import calibration

300ms processing delay

Command syntax

Import: Use this command to upload calibration settings to one or more devices.

Import,n import calibration string to new device

Example

Import, 59 6F 75 20 61 72 (1 of 10)

Import, 65 20 61 20 63 6F (2 of 10)

⋮

Import, 6F 6C 20 67 75 79 (10 of 10)

Response

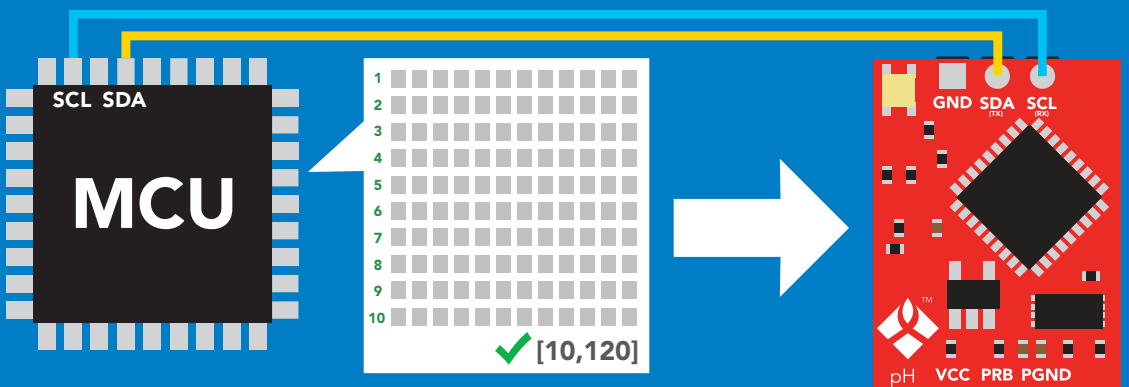
Wait 300ms 1 Dec 0 Null

Wait 300ms 1 Dec 0 Null

⋮

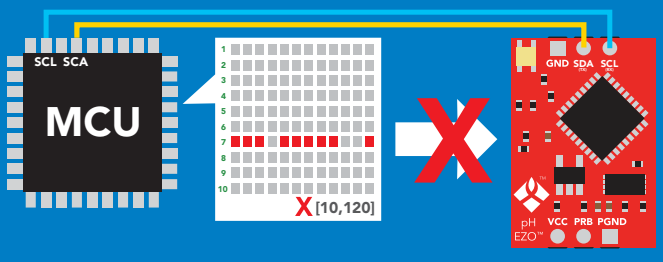
Wait 300ms 1 Dec 0 Null

Import,n



1 Dec *Pending ASCII 0 Null

system will reboot



reboot

*** If one of the imported strings is not correctly entered, the device will not accept the import and reboot.**

Atlas Scientific™ Environmental Robotics

r 0.2

Slope

300ms processing delay

After calibrating a pH probe issuing the slope command will show how closely (in percentage) the calibrated pH probe is working compared to the "ideal" pH probe.

Command syntax

Slope,? returns the slope of the pH probe

Example Response

Slope,?

Wait 300ms

1	?Slope,99.7,100.3, -0.89	0
Dec	ASCII	Null

Response breakdown

?Slope,

99.7

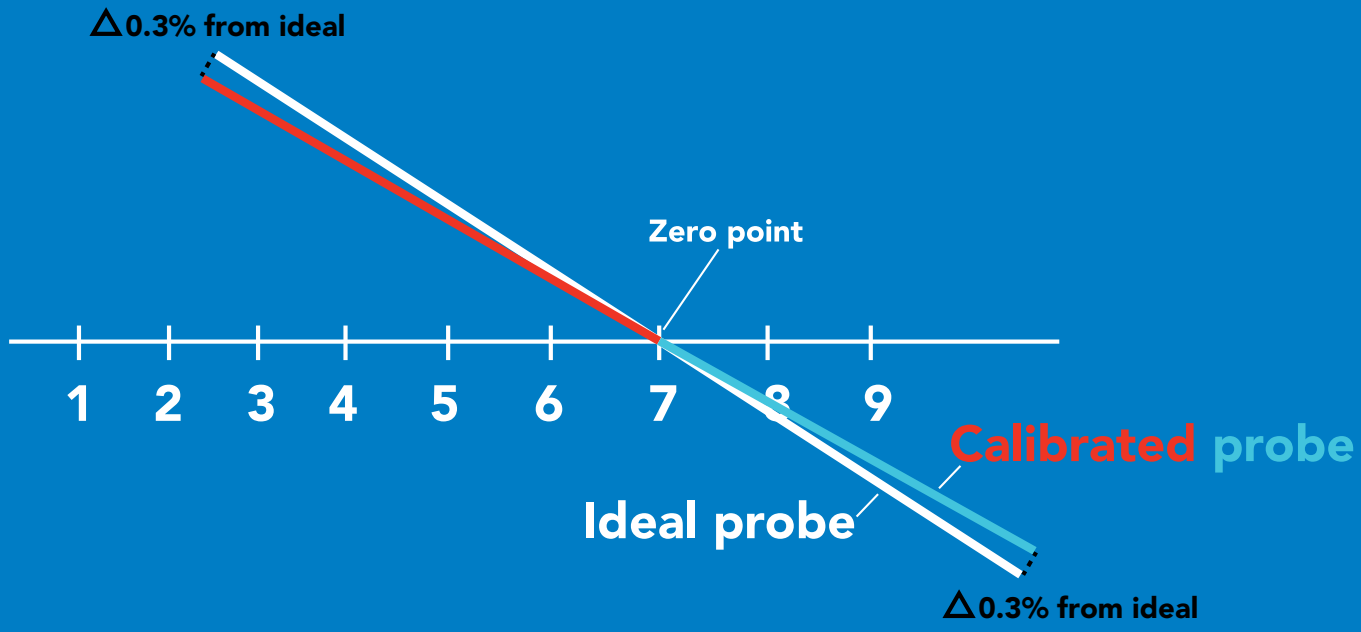
99.7% is how closely the slope of the **acid** calibration line matched the "ideal" pH probe.

100.3

100.3% is how closely the slope of the **base** calibration matches the "ideal" pH probe.

-0.89

This is how many millivolts the zero point is off from true 0.



AtlasScientific™ Environmental Robotics

r 0.1

Extended pH scale

300ms processing delay

Very strong acids and basses can exceed the traditional pH scale. This command extends the pH scale to show below 0 and above 14.

Lowest possible reading: **-1.6**
Highest possible reading: **15.6**

Command syntax

pHext,0	extended pH scale off (0–14)	**default**
pHext,1	extended pH scale on (-1.6–15.6)	
pHext,?	extended pH scale on/off?	

Example	Response
pHext,1	Wait 300ms · 1 (Dec) · 0 (Null)
pHext,0	Wait 300ms · 1 (Dec) · 0 (Null)
pHext,?	Wait 300ms · 1 (Dec) · ?pHext,1 (ASCII) · 0 (Null) **or** 1 (Dec) · ?pHext,0 (ASCII) · 0 (Null)

pHext,0

pH = 0.000

pHext,1

pH = -1.220

Atlas Scientific™ Environmental Robotics

r 0.1

Temperature compensation

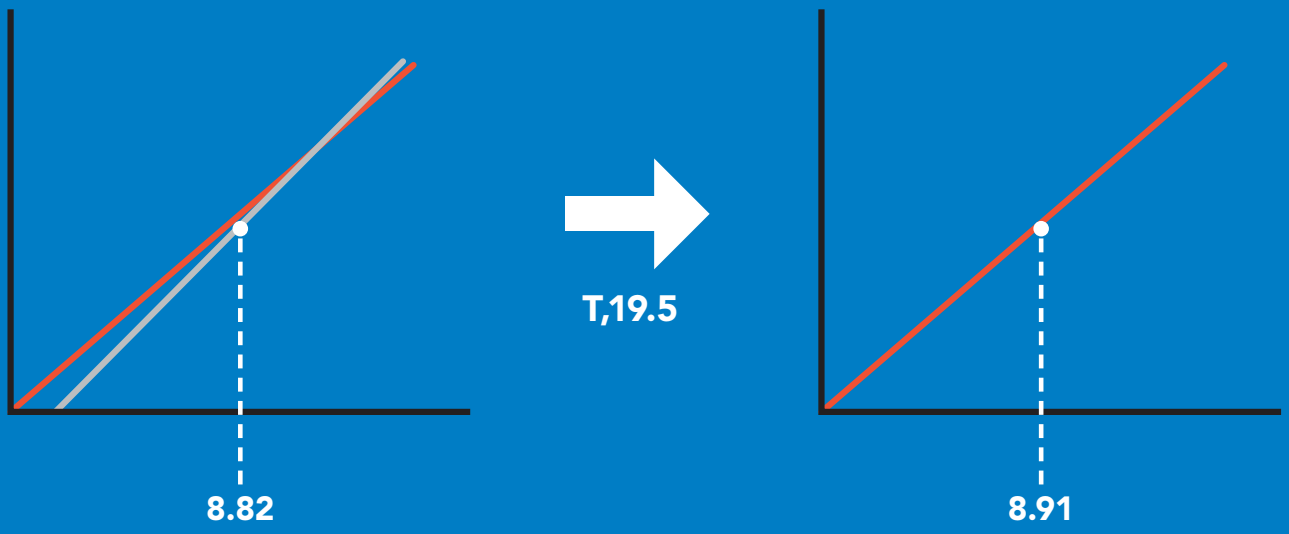
Command syntax

Default temperature = 25°C
Temperature is always in Celsius
Temperature is not retained if power is cut

T,n	n = any value; floating point or int	300ms processing delay
T,?	compensated temperature value?	
RT,n	set temperature compensation and take a reading*	

This is a new command for firmware V2.12

Example	Response
T,19.5	Wait 300ms → 1 (Dec) 0 (Null)
RT,19.5	Wait 900ms → 1 (Dec) 8.91 (ASCII) 0 (Null)
T,?	Wait 300ms → 1 (Dec) ?T,19.5 (ASCII) 0 (Null)



AtlasScientific™ Environmental Robotics

r 0.2

Naming device

300ms processing delay

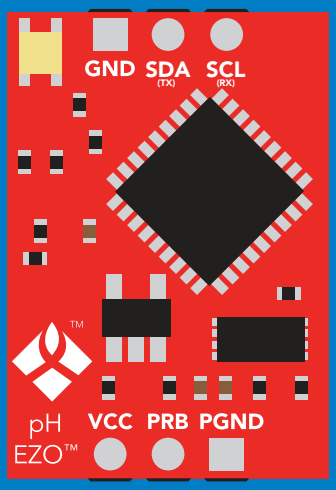
Command syntax

Do not use spaces in the name

Name,n	set name	n = _ _ _ _ _ _ _ _ _ _ _ _ _ _ _ _ (1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16)
Name,?	show name	Up to 16 ASCII characters

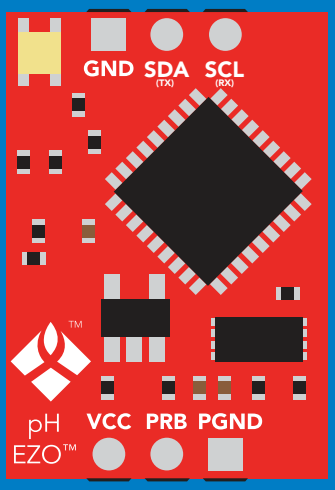
Example	Response
Name,zzt	Wait 300ms → 1 (Dec) 0 (Null)
Name,?	Wait 300ms → 1 (Dec) ?Name,zzt (ASCII) 0 (Null)

Name,zzt



1 0

Name,?



1 ?Name,zzt 0

Atlas Scientific Environmental Robotics

r 0.1

Device information

Command syntax

300ms processing delay

i device information

Example

i

Response

1 Dec

?i,pH,1.98 ASCII

0 Null

Response breakdown

?i, pH, 1.98

pH, ↑ Device

1.98 ↑ Firmware

Reading device status

Command syntax

300ms processing delay

Status voltage at Vcc pin and reason for last restart

Example

Status

Response

1	?Status,P,5.038	0
Dec	ASCII	Null

Response breakdown

?Status, P, 5.038

P, ↑ Reason for restart

5.038 ↑ Voltage at Vcc

Restart codes

P	powered off
S	software reset
B	brown out
W	watchdog
U	unknown

AtlasScientific™ Environmental Robotics

r 0.1

Sleep mode/low power

Command syntax

Sleep	enter sleep mode/low power

Send any character or command to awaken device.

Example	Response
Sleep	no response
Any command	wakes up device

Do not read status byte after issuing sleep command.

	STANDBY	SLEEP
5V	16 mA	1.16 mA
3.3V	13.9 mA	0.995 mA

Standby

Sleep

AtlasScientific™
Environmental Robotics
r 0.1

Protocol lock

Command syntax

300ms processing delay

Plock,1 enable Plock

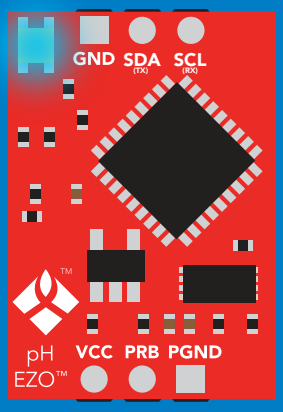
Plock,0 disable Plock **default**

Plock,? Plock on/off?

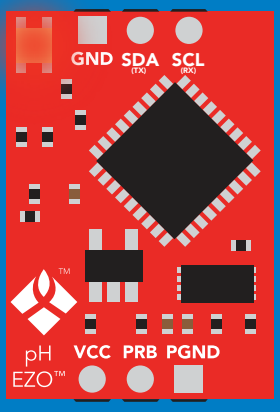
Locks device to I²C mode.

Example	Response
Plock,1	Wait 300ms → 1 (Dec) 0 (Null)
Plock,0	Wait 300ms → 1 (Dec) 0 (Null)
Plock,?	Wait 300ms → 1 (Dec) ?Plock,1 (ASCII) 0 (Null)

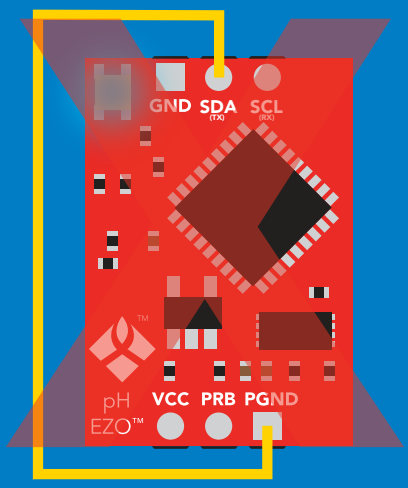
Plock,1



Baud, 9600



cannot change to UART



cannot change to UART

AtlasScientific™ Environmental Robotics

r 0.1

I²C address change

Command syntax

300ms processing delay

I2C,n sets I²C address and reboots into I²C mode

Example	Response
I2C,100	device reboot

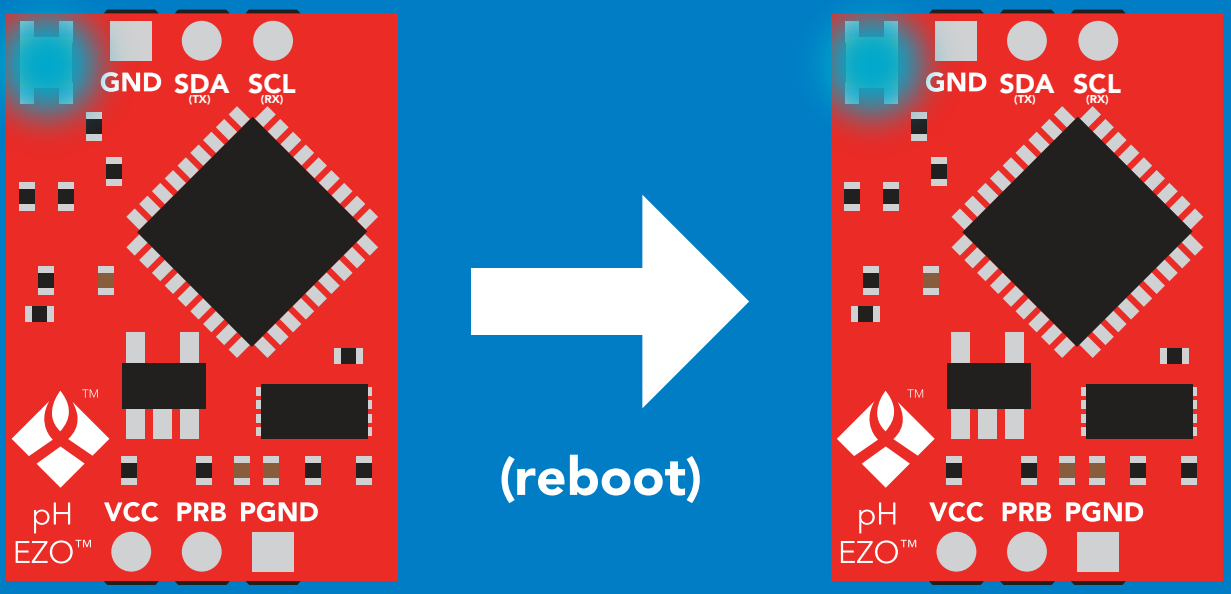
Warning!

Changing the I²C address will prevent communication between the circuit and the CPU until the CPU is updated with the new I²C address.

Default I²C address is 99 (0x63).

n = any number 1 – 127

I2C,100



Atlas Scientific™ Environmental Robotics

r 0.2

Factory reset

Command syntax

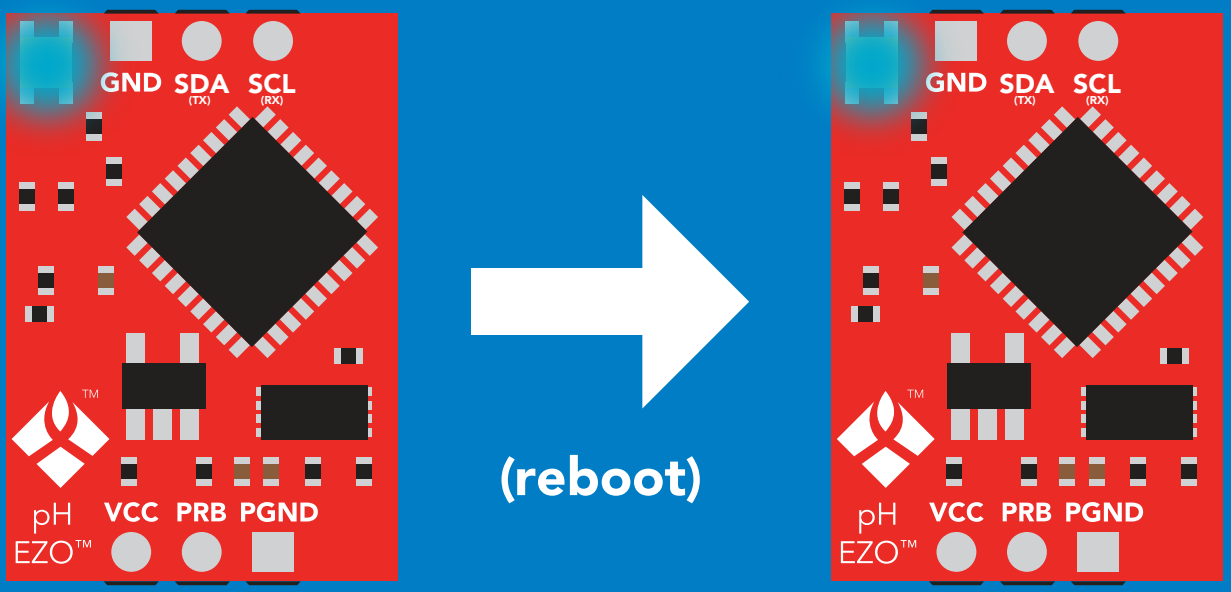
Factory reset will not take the device out of I²C mode.

Factory enable factory reset	I²C address will not change

Example	Response
Factory	device reboot

Clears calibration
LED on
Response codes enabled

Factory



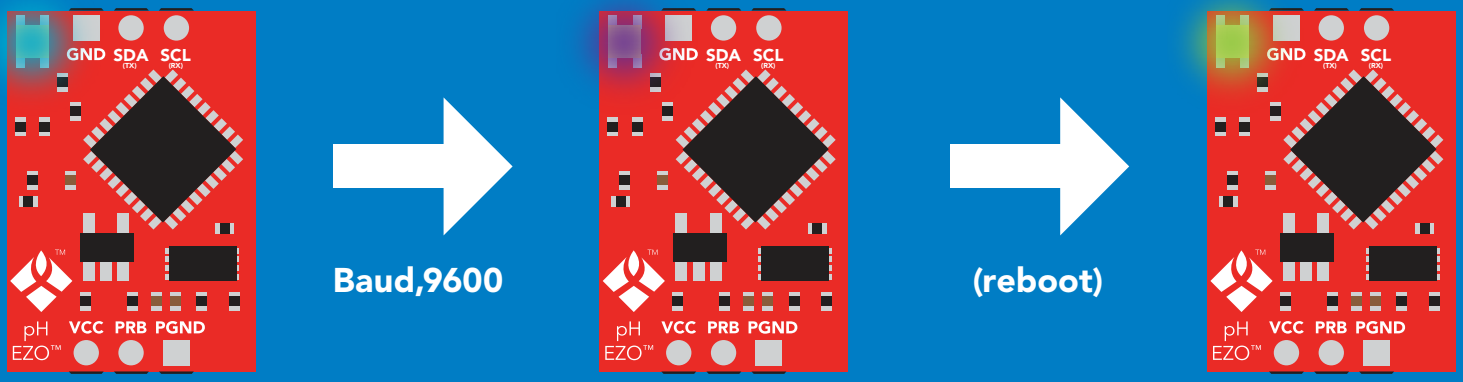
Change to UART mode

Command syntax

Baud,n switch from I²C to UART

Example	Response
Baud,9600	reboot in UART mode

n =
- 300
- 1200
- 2400
- 9600
- 19200
- 38400
- 57600
- 115200

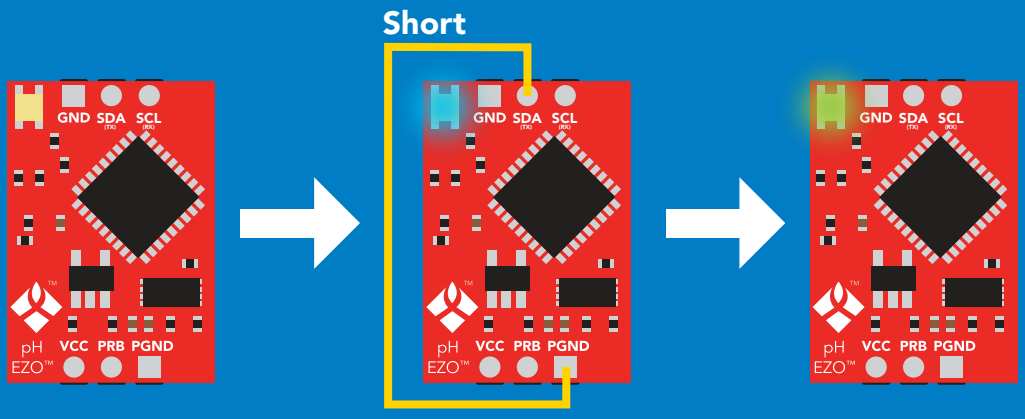


Changing to UART mode

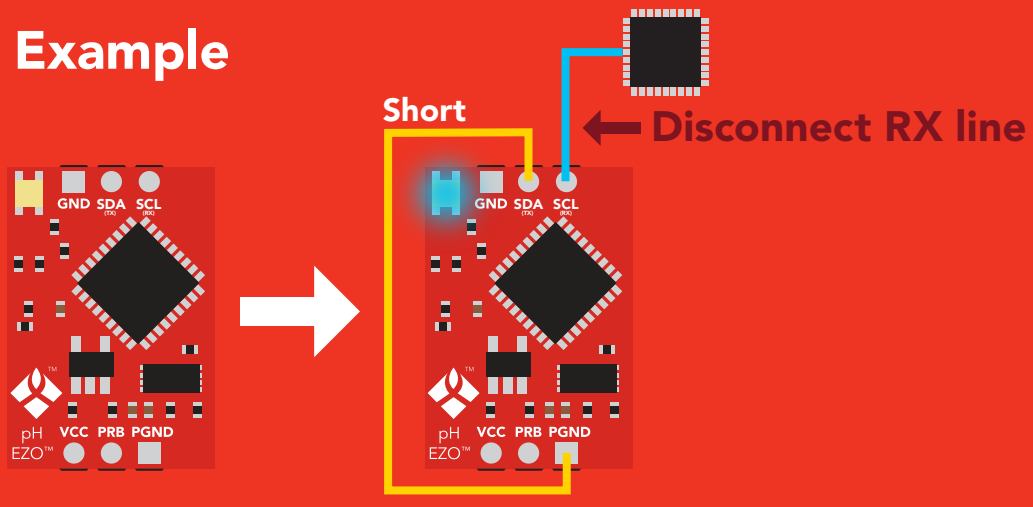
Manual switching to UART

- Disconnect ground (power off)
- Disconnect TX and RX
- Connect TX to PGND
- Confirm RX is disconnected
- Connect ground (power on)
- Wait for LED to change from Blue to Green
- Disconnect ground (power off)
- Reconnect all data and power

Example

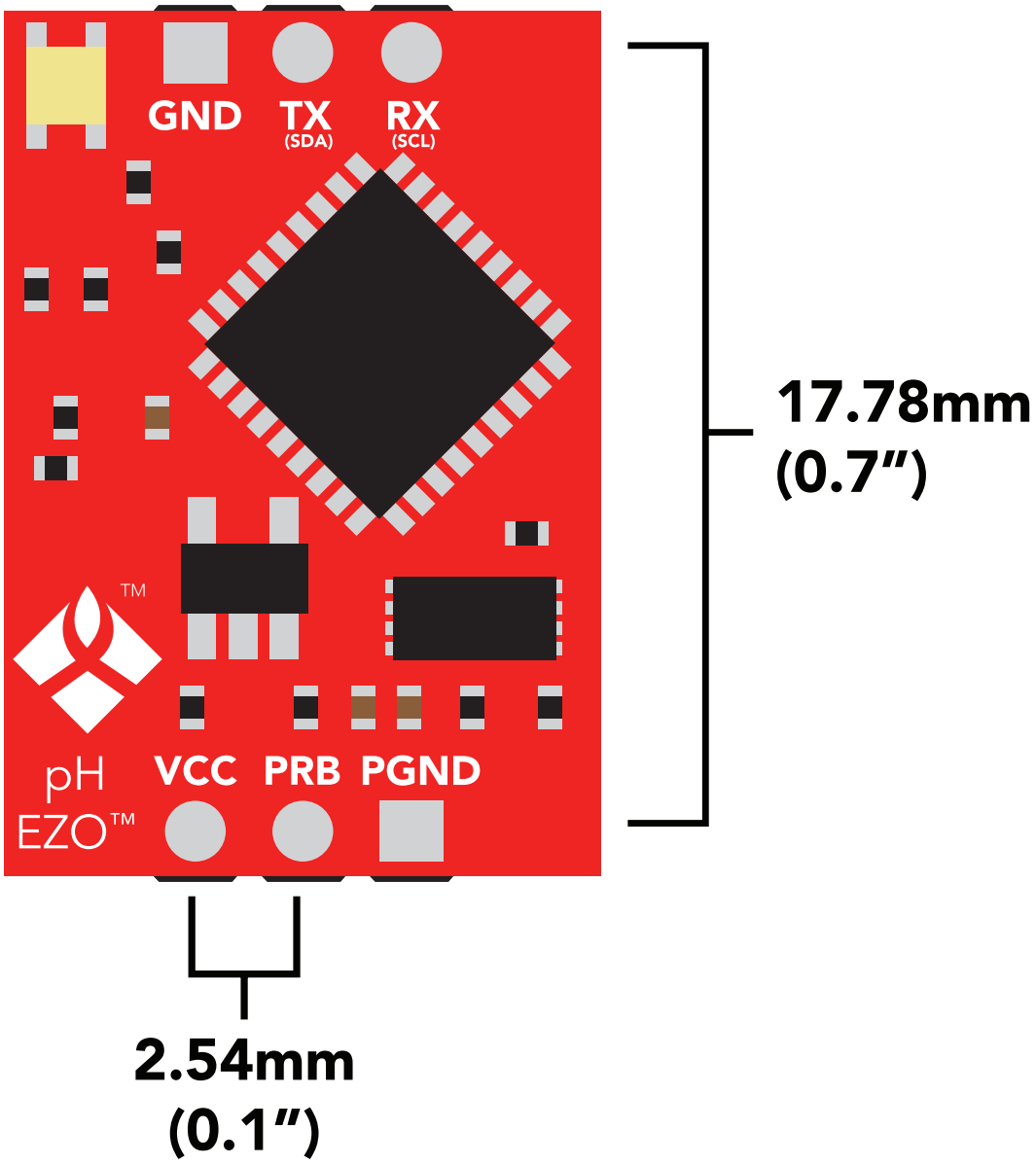


Wrong Example

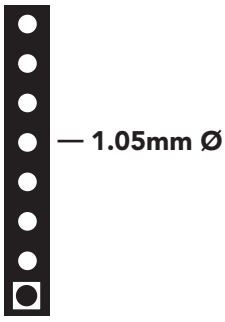


AtlasScientific™
Environmental Robotics
r 0.1

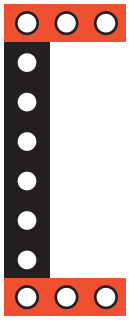
EZO™ circuit footprint



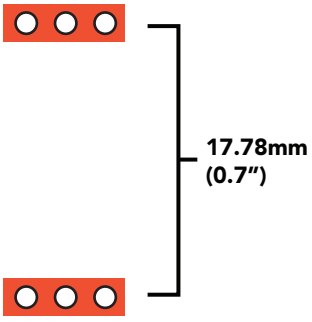
1 In your CAD software place a 8 position header.



2 Place a 3 position header at both top and bottom of the 8 position.



3 Delete the 8 position header. The two 3 position headers are now 17.78mm (0.7”) apart from each other.



AtlasScientific™
Environmental Robotics
r 0.1

Datasheet change log

Datasheet V 5.7

Added new command:
"Extended pH Scale" pages 30 (UART) & 56 (I^2C).

Datasheet V 5.6

Revised information on the slope command found on pages 29 & 54.

Datasheet V 5.5

Revised artwork within datasheet.

Datasheet V 5.4

Moved the Default state to pg 14.

Datasheet V 5.3

Revised response for the sleep command in UART mode on pg 35.

Datasheet V 5.2

Revised calibration theory on page 11, and added more information on the Export calibration and Import calibration commands.

Datasheet V 5.1

Revised isolation schematic on pg 10.

Datasheet V 5.0

Added more information about temperature compensation on pages 29 & 53.

Datasheet V 4.9

Changed "Max rate" to "Response time" on cover page.

Datasheet V 4.8

Added new command:
"RT,n" for Temperature compensation located on pages 29 (UART) & 53 (I^2C).
Added firmware information to Firmware update list.

Datasheet V 4.7

Removed note from certain commands about firmware version.

Datasheet V 4.6

Added information to calibration theory on pg 7.

Datasheet V 4.5

Revised definition of response codes on pg 44.

Datasheet V 4.4

Added resolution range to cover page.

Datasheet V 4.3

Revised isolation information on pg 9.

Datasheet V 4.2

Revised Plock pages to show default value.

Datasheet V 4.1

Added new commands:
"Find" pages 23 (UART) & 46 (I^2C).
"Export/Import calibration" pages 27 (UART) & 49 (I^2C).
Added new feature to continous mode "C,n" pg 24.

Datasheet V 4.0

Added accuracy range on cover page, and revised isolation info on pg. 10.

Datasheet V 3.9

Revised calibration theory on pg. 7.

Datasheet V 3.8

Revised entire datasheet.

Firmware updates

V1.5 – Baud rate change (Nov 6, 2014)
- Change default baud rate to 9600

V1.6 – I²C bug (Dec 1, 2014)
- Fixed I²C bug where the circuit may inappropriately respond when other I²C devices are connected.

V1.7 – Factory (April 14, 2015)
- Changed "X" command to "Factory"

V1.95 – Plock (March 31, 2016)
- Added protocol lock feature "Plock"

V1.96 – EEPROM (April 26, 2016)
- Fixed bug where EEPROM would get erased if the circuit lost power 900ms into startup

V1.97 – EEPROM (Oct 10, 2016)
- Added the option to save and load calibration.

V1.98 – EEPROM (Nov 14, 2016)
- Fixed bug during calibration process.

V2.10 – (May 9, 2017)
- Added "Find" command.
- Added "Export/import" command.
- Modified continuous mode to be able to send readings every "n" seconds.

V2.11 – (June 12, 2017)
- Fixed "I" command to return "pH" instead of "PH".

V2.12 – (April 16, 2018)
- Fixed "cal,clear" was not clearing stored calibration in EEPROM.
- Added "RT" command to Temperature compensation.

V2.13 – (June 25, 2019)
- Added calibration offset to slope.
- Added calibration with temperature compensation.

V2.14 – (June 10, 2020)
- Added extended pH scale

Warranty

Atlas Scientific™ Warranties the EZO™ class pH circuit to be free of defect during the debugging phase of device implementation, or 30 days after receiving the EZO™class pH circuit (which ever comes first).

The debugging phase

The debugging phase as defined by Atlas Scientific™ is the time period when the EZO™ class pH circuit is inserted into a bread board, or shield. If the EZO™ class pH circuit is being debugged in a bread board, the bread board must be devoid of other components. If the EZO™ class pH circuit is being connected to a microcontroller, the microcontroller must be running code that has been designed to drive the EZO™ class pH circuit exclusively and output the EZO™ class pH circuit data as a serial string.

It is important for the embedded systems engineer to keep in mind that the following activities will void the EZO™ class pH circuit warranty:

- **Soldering any part of the EZO™ class pH circuit.**
- **Running any code, that does not exclusively drive the EZO™ class pH circuit and output its data in a serial string.**
- **Embedding the EZO™ class pH circuit into a custom made device.**
- **Removing any potting compound.**

Reasoning behind this warranty

Because Atlas Scientific™ does not sell consumer electronics; once the device has been embedded into a custom made system, Atlas Scientific™ cannot possibly warranty the EZO™ class pH circuit, against the thousands of possible variables that may cause the EZO™ class pH circuit to no longer function properly.

Please keep this in mind:

1. **All Atlas Scientific™ devices have been designed to be embedded into a custom made system by you, the embedded systems engineer.**

2. **All Atlas Scientific™ devices have been designed to run indefinitely without failure in the field.**

3. **All Atlas Scientific™ devices can be soldered into place, however you do so at your own risk.**

Atlas Scientific™ is simply stating that once the device is being used in your application, Atlas Scientific™ can no longer take responsibility for the EZO™ class pH circuits continued operation. This is because that would be equivalent to Atlas Scientific™ taking responsibility over the correct operation of your entire device.

